February 2007

90 dB (typ)

98 dB (typ)



LM49370 Boomer[®] Audio Power Amplifier Series

Audio Sub-System with an Ultra Low EMI, Spread Spectrum, Class D Loudspeaker Amplifier, a Dual-Mode Stereo Headphone Amplifier, and a Dedicated PCM Interface for Bluetooth Transceivers

1.0 General Description

The LM49370 is an integrated audio subsystem that supports both analog and digital audio functions. The LM49370 includes a high quality stereo DAC, a mono ADC, a stereo headphone amplifier, which supports output cap-less (OCL) or AC-coupled (SE) modes of operation, a mono earpiece amplifier, and an ultra-low EMI spread spectrum Class D loudspeaker amplifier. It is designed for demanding applications in mobile phones and other portable devices.

The LM49370 features a bi-directional I²S interface and a bidirectional PCM interface for full range audio on either interface. The LM49370 utilizes an I²C or SPI compatible interface for control. The stereo DAC path features an SNR of 85 dB with an 18-bit 48 kHz input. In SE mode the headphone amplifier delivers at least 33 mW_{RMS} to a 32 Ω single-ended stereo load with less than 1% distortion (THD+N) when A_V_{DD} = 3.3V. The mono earpiece amplifier delivers at least 115mW_{RMS} to a 32 Ω bridged-tied load with less than 1% distortion (THD+N) when A_V_{DD} = 3.3V. The mono speaker amplifier delivers up to 490mW into an 8 Ω load with less than 1% distortion when LS_V_{DD} = 3.3V and up to 1.2W when LS_V_{DD} = 5.0V.

The LM49370 employs advanced techniques to reduce power consumption, to reduce controller overhead, to speed development time, and to eliminate click and pop. Boomer audio power amplifiers were designed specifically to provide high quality output power with a minimal amount of external components. It is therefore ideally suited for mobile phone and other low voltage applications where minimal power consumption, PCB area and cost are primary requirements.

2.0 Applications

- Smart phones
- Mobile Phones and Multimedia Terminals
- PDAs, Internet Appliances and Portable Gaming
- Portable DVD/CD/AAC/MP3 Players
- Digital Cameras/Camcorders

3.0 Key Specifications

- P_{HP (AC-COUP)} (A_V_{DD} = 3.3V, 32Ω, 1% THD) 33 mW
- P_{HP (OCL)} (A_V_{DD} = 3.3V, 32Ω, 1% THD) 31 mW
 P_{LS} (LS_V_{DD} = 5V, 8Ω, 1% THD) 1.2 W
- P_{LS} (LS_ V_{DD} = 5V, 8Ω, 1% THD) 1.2 W ■ P_{LS} (LS_ V_{DD} = 4.2V, 8Ω, 1% THD) 900 mW
- P_{LS} (LS_V_{DD} = 4.2V, 8Ω, 1% THD)
 P_{LS} (LS_V_{DD} = 3.3V, 8Ω, 1% THD)
- Shutdown Current
- PSRR_{LS} (217 Hz, LS_V_{DD} = 3.3V)

- SNR_{LS} (AUX IN to Loudspeaker) 90 dB (typ)
- SNR_{DAC} (Stereo DAC to AUXOUT) 85 dB (typ)
- SNR_{ADC} (Mono ADC from Cell Phone In)
- SNR_{HP} (Aux In to Headphones)

4.0 Features

- Spread Spectrum Class D architecture reduces EMI
- Mono Class D 8Ω amplifier, 490 mW at 3.3V
- OCL or AC-coupled headphone operation
- 33mW stereo headphone amplifier at 3.3V
- 115 mW earpiece amplifier at 3.3V
- 18-bit stereo DAC
- 16-bit mono ADC
- 8 kHz to 192 kHz stereo audio playback
- 8 kHz to 48 kHz mono recording
- Bidirectional I²S compatible audio interface
- Bidirectional PCM compatible audio interface for Bluetooth transceivers
- I²S-PCM Bridge with sample rate conversion
- Sigma-Delta PLL for operation from any clock at any sample rate
- Digital 3D Stereo Enhancement
- FIR filter programmability for simple tone control
- Low power clock network operation if a 12 MHz or 13 MHz system clock is available
- Read/write I²C or SPI compatible control interface
- Automatic headphone & microphone detection
- Support for internal and external microphones
- Automatic gain control for microphone input
- Differential audio I/O for external cellphone module
- Mono differential auxiliary output
- Stereo auxiliary inputs
- Differential microphone input for internal microphone
- Flexible audio routing from input to output
- 32 Step volume control for mixers in 1.5 dB steps
- 16 Step volume control for microphone in 2 dB steps
- Programmable sidetone attenuation in 3 dB steps
- Two configurable GPIO ports
- Multi-function IRQ output
- Micro-power shutdown mode

490 mW

0.8 µA

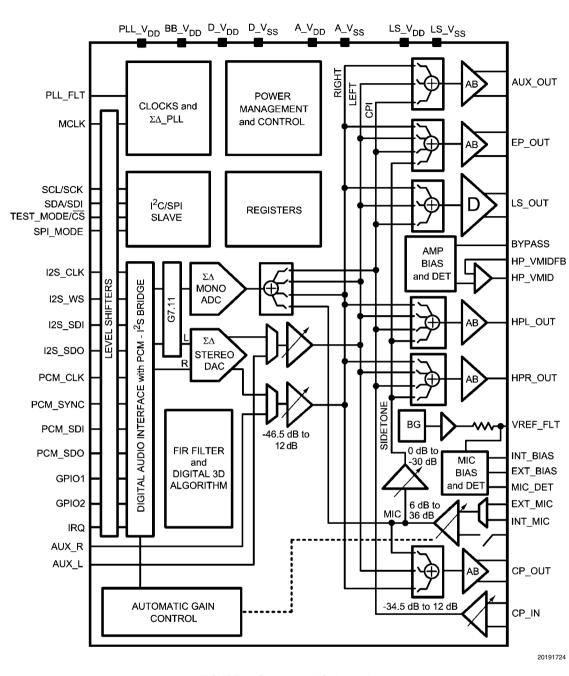
70 dB

Available in the 4 x 4 mm 49 bump micro SMDxt package

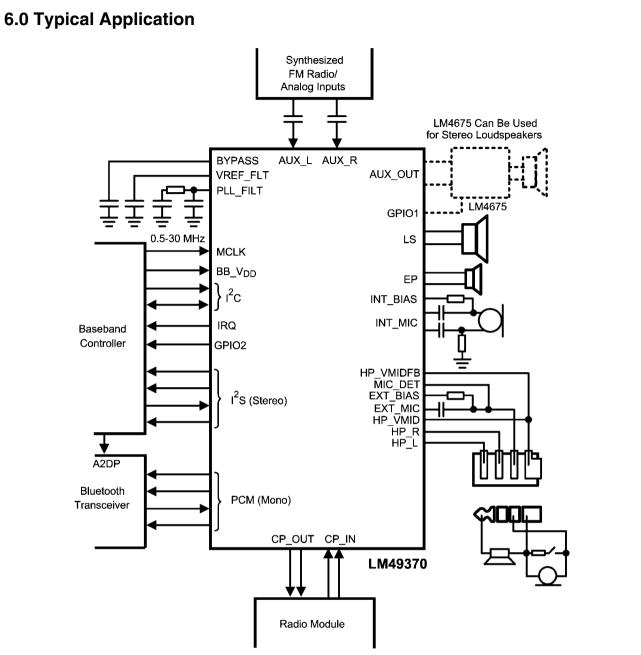
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5.0 LM49370 Overview







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FIGURE 2. Example Application in Multimedia Mobile Phone

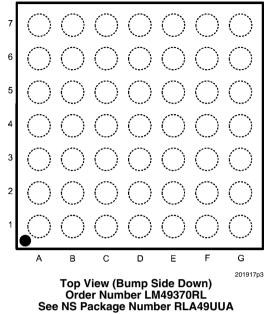
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LM49370

7.0 Connection Diagrams

49 Bump micro SMDxt



49 Bump micro SMDxt Marking



Pin A1

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Pin	Pin Name	Туре	Direction	Description
A1	EP_NEG	Analog	Output	Earpiece negative output
A2	A_V_{DD}	Supply	Input	Headphone and mixer V _{DD}
A3	INT_MIC_POS	Analog	Input	Internal microphone positive input
A4	PCM_SDO	Digital	Output	PCM Serial Data Output
A5	PCM_CLK	Digital	Inout	PCM clock signal
A6	PCM_SYNC	Digital	Inout	PCM sync signal
A7	PCM_SDI	Digital	Input	PCM Serial Data Input
B1	A_V _{SS}	Supply	Input	Headphone and mixer ground
B2	EP_POS	Analog	Output	Earpiece positive output
B3	INT_MIC_NEG	Analog	Input	Internal microphone negative input
B4	BYPASS	Analog	Input	A_V _{DD} /2 filter point
B5	TEST_MODE/CS	Digital	Input	If SPI_MODE = 1, then this pin becomes \overline{CS} .
B6	PLL_FILT	Analog	Input	Filter point for PLL VCO input
B7	PLL_V _{DD}	Supply	Input	PLL V _{DD}
C1	HP_R	Analog	Output	Headphone Right Output
C2	EXT_BIAS	Analog	Output	External microphone supply (2.0/2.5/2.8/3.3V)
C3	INT_BIAS	Analog	Output	Internal microphone supply (2.0/2.5/2.8/3.3V)
C4	AUX_R	Analog	Input	Right Analog Input
C5	GPIO_2	Digital	Inout	General Purpose I/O 2
C6	SDA	Digital	Inout	Control Data, I2C_SDA or SPI_SDA
C7	SCL	Digital	Input	Control Clock, I2C_SCL or SPI_SCL
D1	HP_L	Analog	Output	Headphone Left Output
D2	VREF_FLT	Analog	Inout	Filter point for the microphone power supply
D3	EXT_MIC	Analog	Input	External microphone input
D4	SPI_MODE	Digital	Input	Control mode select 1 = SPI, 0 = I2C
D5	GPIO_1	Digital	Inout	General Purpose I/O 1
D6	BB_V _{DD}	Supply	Input	Baseband V _{DD} for the digital I/Os
D7	D_V _{DD}	Supply	Input	Digital V _{DD}
E1				Virtual Ground for Headphones in OCL mode, otherwise 1st headset detection input
E1 E2	HP_VMID	Analog	Inout	
E3	MIC_DET	Analog	Input	Headset insertion/removal and microphone presence detection input.
E3 E4	AUX_L	Analog	Input	Left Analog Input Cell Phone analog input negative
E4 E5	CPI_NEG IRQ	Analog	Input	Interrupt request signal (NOT open drain)
E5 E6	I2S_SDO	Digital	Output	
E0 E7	125_SD0	Digital Digital	Output Input	I2S Serial Data Out I2S Serial Data Input
E/ F1	HP_VMID_FB	Analog	Input	VMID Feedback in OCL mode, otherwise a 2nd headset detection input
F1		Supply	Input	Loudspeaker V _{DD}
	LS_V _{DD} CPI_POS			
F3		Analog	Input	Cell Phone analog input positive
F4	CPO_NEG	Analog	Output	Cell Phone analog output negative
F5	AUX_OUT_NEG	Analog	Output	Auxiliary analog output negative
F6	I2S_WS	Digital	Inout	I2S Word Select Signal (can be master or slave)
F7	I2S_CLK	Digital	Inout	I2S Clock Signal (can be master or slave)
G1	LS_NEG	Analog	Output	Loudspeaker negative output
G2	LS_V _{SS}	Supply	Input	Loudspeaker ground
G3	LS_POS	Analog	Output	Loudspeaker positive output
G4	CPO_POS	Analog	Output	Cell Phone analog output positive

Pin	Pin Name	Туре	Direction		Desci	ription
G6	D_V _{SS}	Supply	Input	Digital ground		
G7	MCLK	Digital	Input	Input clock from 0.5 M	/Hz to 30 MHz	
7.1 PIN TYPE DEFINITIONS Digital Input— A pin that is used by the digital but is r Analog Input— A pin that is used by the analog and is Digital Input— A pin that is used by the digital but is r					A pin that is used by the digital but is nev- er driven.	
	0	never driven by the device. Supplies are part of this classification.		evice. Supplies are	Digital Output—	A pin that is driven by the device and should not be driven by another device to
Ar	Analog Output— A pin that is driven by the device and should not be driven by external sources.		Digital Inout—	avoid contention. A pin that is either open drain (I2C_SDA)		
Ar	nalog Inout—	DC signal v	within the de	used for filtering a vice, Passive com- cted to these pins.		or a bidirectional CMOS in/out. In the later case the direction is selected by a control register within the LM49370.

8.0 Absolute Maximum Ratings (Notes

1, 2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Analog Supply Voltage	
(A_V _{DD} & LS_V _{DD})	6.0V
Digital Supply Voltage	
(BB_V _{DD} & D_V _{DD} & PLL_V _{DD})	6.0V
Storage Temperature	–65°C to +150°C
Power Dissipation (Note 3)	Internally Limited
ESD Susceptibility	
Human Body Model (Note 4)	2500V
Machine Model (Note 5)	200V

Junction Temperature 150° CThermal Resistance $\theta_{JA} - RLA49$ (soldered down toPCB with $2in^2$ 1oz. copper plane) 60° C/WSoldering Information 40° C/W

9.0 Operating Ratings

Temperature Range	-40°C to +85°C
Supply Voltage	
D_V _{DD} /PLL_V _{DD}	2.5V to 4.5V
BB_V _{DD}	1.8V to 4.5V
LS_V_{DD}/A_V_{DD}	2.5V to 5.5V

10.0 Electrical Characteristics (Notes 1, 2) Unless otherwise stated PLL_V_{DD} = 3.3V, D_V_{DD} = 3.3V, BB_V_{DD} = 1.8V, A_V_{DD} = 3.3V, LS_V_{DD} = 3.3V. The following specifications apply for the circuit shown in *Figure 2* unless otherwise stated. Limits apply for 25°C.

	Parameter	Conditions	LM49		
Symbol			Typical (Note 6)	Limit (Notes 7, 11)	Units
POWER				-	
DI _{SD}	Digital Shutdown Current	Chip Mode '00', f _{MCLK} = 13MHz	0.7	2.2	µA (ma
DI _{ST}	Digital Standby Current	Chip Mode '01', f _{MCLK} = 13MHz	0.9	1.8	mA(ma
ai _{sd}	Analog Shutdown Current	Chip Mode '00'	0.1	1.2	µA(ma
۹I _{ST}	Analog Standby Current	Chip Mode '01'	0.1	1.2	µA (ma
	Digital Playback Mode Digital	Chip Mode '10', $f_{MCLK} = 12MHz$, $f_S = 48kHz$, DAC on; PLL off	7.9		mA
	Active Current	Chip Mode '10', $f_{MCLK} = 13MHz$, $f_{PLLOUT} = 12MHz$, $f_{S} = 48kHz$; DAC + PLL on	12.5	14.5	mA(ma
	Digital Playback Mode Analog Active Current	Chip Mode '10', HP On, SE mode, DAC inputs selected	9.0	13.5	mA(ma
		Chip Mode '10', HP On, OCL mode, DAC inputs selected	9.4	13.5	mA(ma
		Chip Mode '10', LS On, DAC inputs selected	11.5	15.5	mA(ma
	Analog Playback Mode Digital Active Current	Chip Mode '10', f _{MCLK} = 13MHz, DAC +ADC + PLL off	0.9	1.8	mA(ma
		Chip Mode '10', HP On, SE mode, AUX inputs selected	5.9	9.5	mA(ma
	Analog Playback Mode Analog Active Current	Chip Mode '10', HP On, OCL mode, AUX inputs selected	6.3	9.7	mA(ma
		Chip Mode '10', LS On, AUX inputs selected	8.4	12	mA(ma
	CODEC Mode Digital Active Current	Chip Mode '10', f _{MCLK} = 13MHz, f _S = 8kHz, DAC +ADC on; PLL Off	2.7	3.5	mA(ma
	CODEC Mode Analog Active Current	Chip Mode '10', EP On, DAC inputs selected	11.2	15.5	mA(ma
	Voice Module Mode Digital Active Current	Chip Mode '10', f _{MCLK} = 13MHz, DAC +ADC + PLL off	0.9	1.8	mA(ma
	Voice Module Mode Analog Active Current	Chip Mode '10', EP + CPOUT on, CPIN input selected	7.4	11	mA(ma

	Parameter		LM49		
Symbol		Conditions	Typical (Note 6)	Limit (Notes 7, 11)	Units
LOUDSPEAK					
		8Ω load, LS_V _{DD} = 5V	1.2		W
P _{LS}	Max Loudspeaker Power	8Ω load, LS_V _{DD} = 4.2V	0.9		W
		8Ω load, LS_V _{DD} = 3.3V	0.5	0.43	W (mir
LS _{THD+N}	Loudspeaker Harmonic Distortion	8Ω load, $LS_V_{DD} = 3.3V$, $P_{\Omega} = 400mW$	0.04		%
LS _{EFF}	Efficiency	0 dB Input MCLK = 12.000 MHz	84		%
PSRR _{LS}	Power Supply Rejection Ration (Loudspeaker)	AUX inputs terminated $C_{BYPASS} = 1.0 \ \mu F$ $V_{RIPPLE} = 200 \ mV_{P-P}$ $f_{RIPPLE} = 217 \ Hz$	70		dB
SNR _{LS}	Signal to Noise Ratio	From 0 dB Analog AUX input, A-weighted	90	80	dB(min
e _N	Output Noise	A-weighted	62		μV
V _{OS}	Loudspeaker Offset Voltage		12		mV
HEADPHONE				-!	
		32Ω load, 3.3V, SE	33	25	mW (min)
	Headphone Power	16Ω load, 3.3V, SE	52		mW
P _{HP}		32Ω load, 3.3V, OCL, VCM = 1.5V	31		mW
nr		32Ω load, 3.3V, OCL, VCM = 1.2V	20		mW
		16Ω load, 3.3V, OCL, VCM = 1.5V	50		mW
		16Ω load, 3.3V, OCL, VCM = 1.2V	32		mW
		AUX inputs terminated $C_{BYPASS} = 1.0 \ \mu F$ $V_{RIPPLE} = 200 \ mV_{P-P}$ $f_{RIPPLE} = 217 \ Hz$			
PSRR _{HP}	Power Supply Rejection Ratio (Headphones)	SE Mode	60		dB
		OCL Mode VCM = 1.2V	68	55	dB(mir
		OCL Mode VCM = 1.5V	65		dB
		From 0dB Analog AUX input A-weighted			
		SE Mode	98		dB
SNR _{HP}	Signal to Noise Ratio	OCL Mode VCM = 1.2V	97		dB
		OCL Mode VCM = 1.5V	96		dB
HP _{THD+N}	Headphone Harmonic Distortion	32Ω load, $3.3V$, $P_0 = 7.5mW$	0.05		%
e _N	Output Noise	A-weighted	12		μV
ΔA _{CH-CH}	Stereo Channel-to-Channel Gain Mismatch		0.3		dB
X _{TALK}	Stereo Crosstalk	SE Mode	61		dB
MTALK		OCL Mode	71		dB
V _{OS}	Offset Voltage		8		mV

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	Parameter		LM49		
Symbol		Conditions	Typical (Note 6)	Limit (Notes 7, 11)	Units
P _{EP}	Earpiece Power	32Ω load, 3.3V	115	100	mW (min)
EP		16Ω load, 3.3V	150		mW
PSRR _{EP}	Power Supply Rejection Ratio (Earpiece)	$CP_IN \text{ terminated}$ $C_{BYPASS} = 1.0 \ \mu\text{F}$ $V_{RIPPLE} = 200 \ mV_{P-P}$ $F_{RIPPLE} = 217 \ Hz$	76		dB
SNR _{EP}	Signal to Noise Ratio	From 0dB Analog AUX input, A-weighted	93		dB
EP _{THD+N}	Earpiece Harmonic Distortion	32Ω load, 3.3V, P _O = 50mW	0.04		%
e _N	Output Noise	A-weighted	41		μV
V _{OS}	Offset Voltage		8		mV
	-	I	-	- <u>I</u>	
THD+N	Total Harmonic Distortion + Noise	$V_{O} = 1V_{RMS}$, 5k Ω load	0.02		%
PSRR	Power Supply Rejection Ratio	$CP_{INS} = 1.0 \mu F$ $V_{RIPPLE} = 200 m VPP$ $f_{RIPPLE} = 217 Hz$	86		dB
CP_OUT AM		1 1			
THD+N	Total Harmonic Distortion + Noise	$V_{O} = 1V_{RMS}$, 5k Ω load	0.02		%
PSRR	Power Supply Rejection Ratio	$C_{BYPASS} = 1.0 \mu F$ $V_{RIPPLE} = 200 m V P P$ $f_{RIPPLE} = 217 H z$	86		dB
MONO ADC	•	- 1		-	
R _{ADC}	ADC Ripple		±0.25		dB
PB _{ADC}	ADC Passband	Lower (HPF Mode 1), f _S = 8 kHz	300		Hz
ADC		Upper	3470		Hz
SBA _{ADC}	ADC Stopband Attenuation	Above Passband	60		dB
-	ADC Stopbard Attendation	HPF Notch, 50 Hz/60 Hz (worst case)	58		dB
SNR _{ADC}	ADC Signal to Noise Ratio	From CPI, A-weighted	90		dB
ADC	ADC Full Scale Input Level		1		V _{RMS}
STEREO DAG	C				
R _{DAC}	DAC Ripple		0.1		dB
PB _{DAC}	DAC Passband		20		kHz
SBA _{DAC}	DAC Stopband Attenuation		70		dB
SNR _{DAC}	DAC Signal to Noise Ratio	A-weighted, AUXOUT	85		dB
DR _{DAC}	DAC Dynamic Range		96		dB
DAC	DAC Full Scale Output Level		1		V _{RMS}
PLL	•	· · ·		I	
F _{IN}	Input Frequency Range	Min Max		0.5	MHz MHz
I2S/PCM	_1	maa		00	
		f _S = 48kHz; 16 bit mode	1.536		MHz
		$f_s = 48$ kHz; 25 bit mode	2.4		MHz
f _{I2SCLK}	I2S CLK Frequency	$f_{\rm S} = 8$ kHz; 16 bit mode	0.256		MHz
		$f_{\rm S} = 8$ kHz; 25 bit mode	0.230	-	MHz

	Parameter	Conditions	LM49		
Symbol			Typical (Note 6)	Limit (Notes 7, 11)	Units
		f _s = 48kHz; 16 bit mode	0.768		MHz
		f _S = 48kHz; 25 bit mode	1.2		MHz
f _{PCMCLK}	PCM CLK Frequency	f _s = 8kHz; 16 bit mode	0.128		MHz
		f _s = 8kHz; 25 bit mode	0.2		MHz
DO		Min		40	% (min
DC _{I2S_CLK}	I2S_CLK Duty Cycle	Мах		60	% (max
DC _{I2S_WS}	I2S_WS Duty Cycle		50		%
12C					-
T _{I2CSET}	I2C Data Setup Time	Refer to Pg. 16 for more details		100	ns (min
T _{I2CHOLD}	I2C Data Hold Time	Refer to Pg. 16 for more details		300	ns (min
SPI					
T _{SPISETENB}	Enable Setup Time			100	ns (min
T _{SPIHOLD-ENB}	Enable Hold Time			100	ns (min
T _{SPISETD}	Data Setup Time			100	ns (min
T _{SPIHOLDD}	Data Hold Time			100	ns (min
T _{SPICL}	Clock Low Time			500	ns (min
T _{SPICH}	Clock High Time			500	ns (min
VOLUME CO	NTROL				
	AUX Volume Control Range	Minimum Gain w/ AUX_BOOST OFF	-46.5		dB
VCR _{AUX}		Maximum Gain w/ AUX_BOOST OFF	0		dB
AUX		Minimum Gain w/ AUX_BOOST ON	-34.5		dB
		Maximum Gain w/ AUX_BOOST ON	12		dB
		Minimum Gain w/ DAC_BOOST OFF	-46.5		dB
VCR _{DAC}	DAC Volume Control Range	Maximum Gain w/ DAC_BOOST OFF	0		dB
DAC		Minimum Gain w/ DAC_BOOST ON	-34.5		dB
		Maximum Gain w/ DAC_BOOST ON	12		dB
VCR _{CPIN}	CPIN Volume Control Range	Minimum Gain	-34.5		dB
CFIN		Maximum Gain	12		dB
VCR _{MIC}	MIC Volume Control Range	Minimum Gain	6		dB
WIC		Maximum Gain	36		dB
VCR _{SIDE}	SIDETONE Volume Control Range	Minimum Gain	-30		dB
		Maximum Gain	0		dB
SS _{AUX}	AUX VCR Stepsize		1.5		dB
SS _{DAC}	DAC VCR Stepsize		1.5		dB
SS _{CPIN}	CPIN VCR Stepsize		1.5		dB
SS _{MIC}	MIC VCR Stepsize		2		dB
SS _{SIDE}	SIDETONE VCR Stepsize		3	<u> </u>	dB
AUDIO PATH	GAIN W/ STEREO (bit 6 of 0x00h) EN	ABLED (AUX_L & AUX_R signals identic	1	ed onto mi	
		Minimum Gain from AUX input, BOOST OFF	-34.5	ļ	dB
	Loudspeaker Audio Path Gain	Maximum Gain from AUX input, BOOST OFF	12		dB
		Minimum Gain from CPI input	-22.5		dB
		Maximum Gain from CPI input	24		dB

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Symbol	Parameter	Conditions	Typical (Note 6)	Limit (Notes 7, 11)	Units
		Minimum Gain from AUX input, BOOST OFF	-52.5		dB
		Maximum Gain from AUX input, BOOST OFF	-6		dB
		Minimum Gain from CPI input	-40.5		dB
	Headphone Audio Path Gain	Maximum Gain from CPI input	6		dB
		Minimum Gain from MIC input using SIDETONE path w/ VCR _{MIC} gain = 6dB	-30		dB
		Maximum Gain from MIC input using SIDETONE path w/ VCR _{MIC} gain = 6dB	0		dB
		Minimum Gain from AUX input, BOOST OFF	-40.5		dB
	Earpiece Audio Path Gain	Maximum Gain from AUX input, BOOST OFF	6		dB
		Minimum Gain from CPI input	-28.5		dB
		Maximum Gain from CPI input	18		dB
		Minimum Gain from MIC input using SIDETONE path w/ VCR _{MIC} gain = 6dB	-18		dB
		Maximum Gain from MIC input using SIDETONE path w/ VCR _{MIC} gain = 6dB	12		dB
		Minimum Gain from AUX input, BOOST OFF	-46.5		dB
	AUXOUT Audio Path Gain	Maximum Gain from AUX input, BOOST OFF	0		dB
		Minimum Gain from CPI input	-34.5		dB
		Maximum Gain from CPI input	12		dB
		Minimum Gain from AUX input, BOOST OFF	-46.5		dB
	CPOUT Audio Path Gain	Maximum Gain from AUX input, BOOST OFF	0		dB
		Minimum Gain from MIC input	6		dB
		Maximum Gain from MIC input	36		dB

			LM49370		
Symbol	Parameter	Conditions	Typical (Note 6)	Limit (Notes 7, 11)	Units
otal DC Pov	ver Dissipation				
		DAC (f _S = 48kHz) and HP ON			
	Digital Playback Mode Power	f _{MCLK} = 12MHz, PLL OFF	56		mW
	Dissipation	f _{MCLK} = 13MHz, PLL ON f _{PLLOUT} = 12MHz	71		mW
	Analog Playback Mode Power	AUX Inputs selected and HP ON			
	Dissipation	f _{MCLK} = 13MHz, PLL OFF	22		mW
	VOICE CODEC Mode Power	PCM DAC ($f_S = 8kHz$) + ADC ($f_S = 8kHz$) and EP ON			
	Dissipation	f _{MCLK} = 13MHz, PLL OFF	46		mW
	VOICE Madula Mada Dawar Dissipation	CP IN selected. EP and CPOUT ON			
	VOICE Module Mode Power Dissipation	f _{MCLK} = 13MHz, PLL OFF	27		mW

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional but do not guarantee specific performance limits.

Characteristics state DC and AC electrical specifications under particular test conditions which guarantee specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not guaranteed for parameters where no limit is given, however, the typical value is a good indication of device performance.

Note 2: All voltages are measured with respect to the relevant V_{SS} pin unless otherwise specified. All grounds should be coupled as close as possible to the device.

Note 3: The maximum power dissipation must be de-rated at elevated temperatures and is dictated by TJ_{MAX} , θ_{JA} , and the ambient temperature, T_A . The maximum allowable power dissipation is $P_{DMAX} = (T_{JMAX} - T_A)/\theta_{JA}$ or the number given in Absolute Maximum Ratings, whichever is lower.

Note 4: Human body model: 100pF discharged through a 1.5k Ω resistor.

Note 5: Machine model: 220pF – 240pF discharged through all pins.

Note 6: Typical values are measured at 25°C and represent the parametric norm.

Note 7: Limits are guaranteed to Nationals AOQL (Average Outgoing Quality Level).

Note 8: Best operation is achieved by maintaining $3.0V < A_V_{DD} < 5.0$ and $3.0V < D_V_{DD} < 3.6V$ and $A_V_{DD} > D_V_{DD}$.

Note 9: Digital shutdown current is measured with system clock set for PLL output while the PLL is disabled.

Note 10: Disabling or bypassing the PLL will usually result in an improvement in noise measurements.

Note 11: Datasheet min/max specification limits are guaranteed by design, test, or statistical analysis.

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11.0 System Control

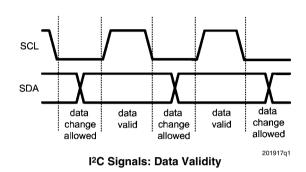
Method 1. I²C Compatible Interface

11.1 I²C SIGNALS

In I²C mode the LM49370 pin SCL is used for the I²C clock SCL and the pin SDA is used for the I²C data signal SDA. Both these signals need a pull-up resistor according to I²C specification. The I²C slave address for LM49370 is **0011010**₂.

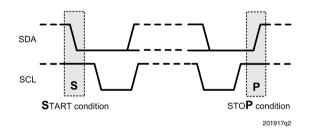
11.2 I²C DATA VALIDITY

The data on SDA line must be stable during the HIGH period of the clock signal (SCL). In other words, state of the data line can only be changed when SCL is LOW.



11.3 I²C START AND STOP CONDITIONS

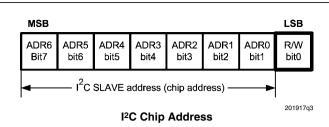
START and STOP bits classify the beginning and the end of the I²C session. START condition is defined as SDA signal transitioning from HIGH to LOW while SCL line is HIGH. STOP condition is defined as the SDA transitioning from LOW to HIGH while SCL is HIGH. The I²C master always generates START and STOP bits. The I²C bus is considered to be busy after START condition and free after STOP condition. During data transmission, I²C master can generate repeated START conditions. First START and repeated START conditions are equivalent, function-wise.



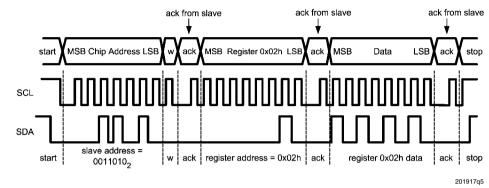
11.4 TRANSFERRING DATA

Every byte put on the SDA line must be eight bits long, with the most significant bit (MSB) being transferred first. Each byte of data has to be followed by an acknowledge bit. The acknowledge related clock pulse is generated by the master. The transmitter releases the SDA line (HIGH) during the acknowledge clock pulse. The receiver must pull down the SDA line during the 9th clock pulse, signifying an acknowledge. A receiver which has been addressed must generate an acknowledge after each byte has been received.

After the START condition, the I²C master sends a chip address. This address is seven bits long followed by an eight bit which is a data direction bit (R/W). The LM49370 address is **0011010**₂. For the eighth bit, a "0" indicates a WRITE and a "1" indicates a READ. The second byte selects the register to which the data will be written. The third byte contains data to write to the selected register.



Register changes take an effect at the SCL rising edge during the last ACK from slave.

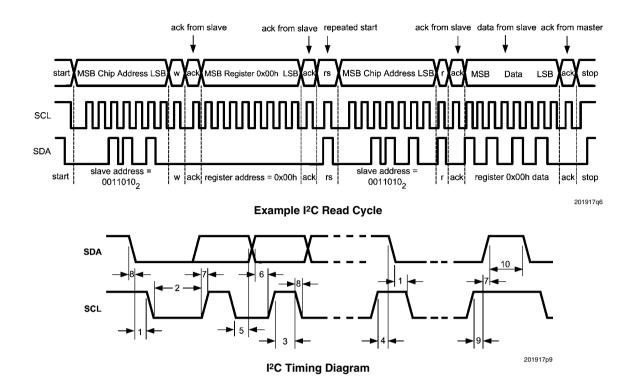


w = write (SDA = "0") r = read (SDA = "1") ack = acknowledge (SDA pulled down by slave) rs = repeated start

Example I²C Write Cycle

LM49370

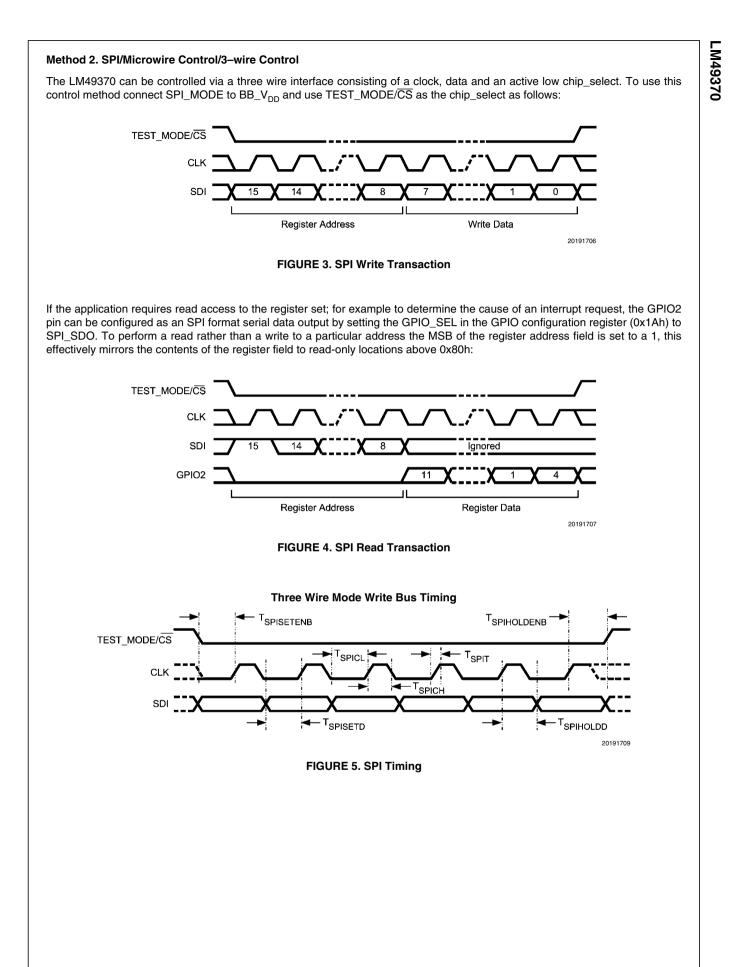
When a READ function is to be accomplished, a WRITE function must precede the READ function, as shown in the Read Cycle waveform.



11.5 I²C TIMING PARAMETERS

Symbol	Parameter	Lin	Limit		
		Min	Мах	1	
1	Hold Time (repeated) START Condition	0.6		μs	
2	Clock Low Time	1.3		μs	
3	Clock High Time	600		ns	
4	Setup Time for a Repeated START Condition	600		ns	
5	Data Hold Time (Output direction, delay generated by LM49370)	300	900	ns	
5	Data Hold Time (Input direction, delay generated by the Master)	0	900	ns	
6	Data Setup Time	100		ns	
7	Rise Time of SDA and SCL	20+0.1C _b	300	ns	
8	Fall Time of SDA and SCL	15+0.1C _b	300	ns	
9	Set-up Time for STOP condition	600		ns	
10	Bus Free Time between a STOP and a START Condition	1.3		μs	
C _b	Capacitive Load for Each Bus Line	10	200	pF	

NOTE: Data guaranteed by design



12.0 Status & Control Registers

TABLE 1. Register Map

(The	default value of	all I2C registe	rs is 0x00h)		Register Map					
Addre ss	Register	7	6	5	4	3	2	1	0	
0x00h	BASIC	DAC_	MODE	CAP	_SIZE	OSC_ENB	PLL_ENB	CHP_I	NODE	
0x01h	CLOCKS			R_C	NV			DAC_CI	_K_SEL	
0x02h	PLL_M	FORCERQ				PLL_M				
0x03h	PLL_N		-		PLL	_N				
0x04h	PLL_P	VCOFATS		Q_DIV			PLI	PLL_P		
0x05h	PLL_MOD	PLLTEST	PLL_CL	K_SEL			PLL_N_MOD			
0x06h	ADC_1	HPF_	MODE	SAMPL	E_RATE	RIGHT	LEFT	CPI	MIC	
0x07h	ADC_2	NGZXDD	ADC_CL	K_SEL		PEAKTIME	-	ADCMUTE	ADC_MOD E	
0x08h	AGC_1	NOISE	_GATE_THRE	SHOLD	NG_ENB		AGC_TARGE	Т	AGC_ENB	
0x09h	AGC_2	AGC_TIGH T	A	AGC_DECAY			AGC_MA	AX_GAIN	•	
0x0Ah	AGC_3		AGC_ATTACK			AG	C_HOLD_TI	ME		
0x0Bh	MIC_1		INT_EXT	SE_DIFF	MUTE		PREAM	P_GAIN		
0x0Ch	MIC_2			BTN_DEBO	UNCE_TIME	BTNTYPE	MIC_BIAS	_VOLTAGE	VCMVOLT	
0x0Dh	SIDETONE						SIDETON	E_ATTEN		
0x0Eh	CP_INPUT			MUTE			CPI_LEVEL			
0x0Fh	AUX_LEFT	AUX_DAC	MUTE	BOOST		AU	X_LEFT_LEV	/EL		
0x10h	AUX_RIGHT	AUX_DAC	MUTE	BOOST	AUX_RIGHT_LEVEL					
0x11h	DAC	USAXLVL	DACMUTE	BOOST	DOST DAC_LEVEL					
0x12h	CP_OUTPUT				MICGATE	MUTE	LEFT	RIGHT	MIC	
0x13h	AUX OUTPUT					MUTE	LEFT	RIGHT	CPI	
0x14h	LS_OUTPUT					MUTE	LEFT	RIGHT	CPI	
0x15h	HP_OUTPUT		OCL	STEREO	MUTE	LEFT	RIGHT	CPI	SIDE	
0x16h	EP_OUTPUT				MUTE	LEFT	RIGHT	CPI	SIDE	
0x17h	DETECT			HS_DBN	C_TIME	•	TEMP_INT	BTN_INT	DET_INT	
0x18h	STATUS		GPIN1	GPIN2	TEMP	BTN	MIC	STEREO	HEADSET	
0x19h	3D	CUST_COM P	ATTENUATE	FR	IEQ	LE	/EL	MODE	3DENB	
0x1Ah	I2SMODE	WORD_ ORDER	I2S_WS_GI	EN_MODE	WS_MS	STEREO REVERSE	I2S_MODE	INENB	OUTENB	
0x1Bh	I2SCLOCK	PCM_SYN	C_WIDTH		I2S_CLOCK_	_GEN_MODE		CLKSCE	CLK_MS	
0x1Ch	PCMMODE	ALAW/ µLAW	COMPAND	SDO_ LSB_HZ	SYNC_MS	CLKSRCE	CLK_MS	INENB	OUTENB	
0x1Dh	PCMCLOCK		PCM_S	YNC_GEN_I	MODE		PCM_CLOCI	KGEN MODE		
0x1Eh	BRIDGE	MONO_S	UM_MODE	MONO_ SUM_SEL	DAC_T	X_SEL	I2S_T	X_SEL	PCM_ TX_SEL	
0x1Fh	GPIO	DAC_SRC_ MODE	ADC_SRC_ GPIO_2_SEL GPIO_1_SEL MODE			·				
0x20h	CMP_0_LSB				CMP_0	_LSB				
0x21h	CMP_0_0SB				CMP_0	_MSB				
0x22h			CMP_1_LSB							
0x23h					CMP_1	_MSB				
0x24h					CMP_2					
	CMP_2_MSB				 CMP_2					
		Į								

12.1 BASIC CONFIGURATION REGISTER

This register is used to control the basic function of the chip.

TABLE 2. BASIC (0x00h)

Bits	Field			Description	
1:0	CHIP_MODE	is selected the LM493	LM49370 can be placed in one of four modes which dictate its basic operation. When a lected the LM49370 will change operation silently and will re-configure the power man le automatically. The modes are described as follows:		
		CHIP MODE	Audio System	Typical Application	
		002	Off	Power-down Mode	
		012	Off	Stand-by mode with headset event detection	
		10 ₂	On	Active without headset event detection	
		11 ₂	On	Active with headset event detection	
2	PLL_ENABLE	This enables the PLL			
3	USE_OSC	will resort to using an o such as click and pop	on-chip oscillator for he . The PLL, ADC, and I	rcuits will assume that no external clock is available and adset detection and analog power management functions DAC are not wired to use this low quality clock. This bit d off power-down mode.	
5:4	CAP_SIZE	This programs the ext size of the bypass cap CAP_SIZE		tabilize once charge/discharge is complete, based on the Turn-off/on time	
		002	0.1 μF	45 ms/75 ms	
		012	1 μF	45 ms/140 ms	
		102	2.2 µF	45 ms/260 ms	
		112	4.7 μF	45 ms/500 ms	
7:6	DAC_MODE			If an "fs*2 ^N " audio clock is available, then the DAC can a clock is not available, the PLL can be used to generate	
		DAC MODE	DAC OSR	Typical Application	
		002	125	48kHz Playback from 12.000MHz	
		012	128	48kHz Playback from 12.288MHz	
		102	64	96kHz Playback from 12.288MHz	
		11 ₂	32	192kHz Playback from 24.576MHz	

For reliable headset / push button detection the following bits should be defined before enabling the headset detection system by setting bit 0 of CHIP_MODE:

The OCL-bit (Cap / Capless headphone interface; bit 6 of HP_OUTPUT (0x15h))

The headset insert/removal debounce settings (bits 6:3 of DETECT (0x17h))

The BTN_TYPE-bit (Parallel / Series push button type; bit 3 MIC_2 register (0x0Ch))

The parallel push button debounce settings (bits 5:4 of MIC_2 register (0x0Ch))

All register fields controlling the audio system should be defined before setting bit 1 of CHIP_MODE and should not be altered while the audio sub-system is active.

If the analog or digital levels are below -12dB then it is not necessary to set the stereo bit allowing greater output levels to be obtained for such signals.

12.2 CLOCKS CONFIGURATION REGISTER

This register is used to control the clocks throughout the chip.

Bits	Field	Desci	ription			
1:0	DAC_CLK This selects the clock to be used by the audio DAC system.		ystem.			
		DAC_CLK	DAC Input Source			
		002	MCLK			
		002	PLL_OUTPUT			
		102	I2S_CLK_IN			
		112	PCM_CLK_IN			
7:2	R_DIV	This programs the R divider.	l			
		R_DIV	Divide Value			
		0	Bypass			
		1	Bypass			
		2	1.5			
		3	2			
		4	2.5			
		5	3			
		6	3.5			
		7	4			
		8	4.5			
		9	5			
		10	5.5			
		11	6			
		12	6.5			
		13 to 61	7 to 31			
		62	31.5			
		63	32			

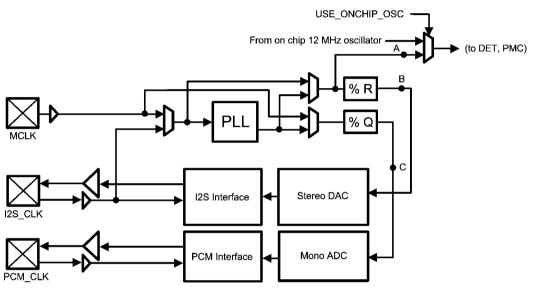
TABLE 3. CLOCKS (0x01h)

12.3 LM49370 CLOCK NETWORK

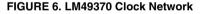
The audio ADC operates at 125*fs (or 128*fs), so it requires a 1.000 MHz (or 1.024MHz) clock to sample at 8 kHz (at point **C** as marked on the following diagram). If the stereo DAC is running at 125*fs (or128*fs), it requires a 12.000MHz (or 1.2.288MHz) clock (at point **B**) for 48 kHz data. It is expected that the PLL is used to drive the audio system operating at 125*fs unless a 12.000 MHz master clock is supplied or the sample rate is always a multiple of 8 kHz. In this case the PLL can be bypassed to reduce power, with clock division being performed by the Q and R dividers instead. The PLL can also be bypassed if the system is running at 128*fs and a 12.288MHz master clock is supplied and the sample rate is a multiple of 8 kHz. The PLL can also use the I²S clock input as a source. In this case, the audio DAC uses the clock from the output of the PLL and the audio ADC either uses the PLL output divided by 2*F_{S(ADC)}/F_{S(ADC)} or a system clock divided by Q, this allows n*8 kHz recording and 44.1 kHz playback.

MCLK must be less than or equal to 30 MHz. I2S_CLK and PCM_CLK should be below 6.144MHz.

When operating at 125*fs, the LM49370 is designed to work from a 12.000 MHz or 11.025 MHz clock at point **A**. When operating at 128*fs, the LM49370 is designed to work from a 12.288MHz or 11.2896 MHz clock at point A. This is used to drive the power management and control logic. Performance may not meet the electrical specifications if the frequency at this point deviates significantly beyond this range.



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12.4 COMMON CLOCK SETTINGS FOR THE DAC & ADC

When DAC_MODE = '00' (bits 7:6 of (0x00h)), the DAC has an over sampling ratio of 125 but requires a 250^{+} fs clock at point **B**. This allows a simple clocking solution as it will work from 12.000 MHz (common in most systems with Bluetooth or USB) at 48 kHz exactly, the following table describes the clock required at point **B** for various clock sample rates in the different DAC modes:

DAC Sample Rate (kHz)	Clock Required at B (OSR = 125)	Clock Required at B (OSR = 128)
8	2 MHz	2.048 MHz
11.025	2.75625 MHz	2.8224 MHz
12	3 MHz	3.072 MHz
16	4 MHz	4.096 MHz
22.05	5.5125 MHz	5.6448 MHz
24	6 MHz	6.144 MHz
32	8 MHz	8.192 MHz
44.1	11.025 MHz	11.2896 MHz
48	12 MHz	12.288 MHz

TABLE 4. Common DAC Clock Frequencies

Note: When DAC_MODE = '01' with the I²S or PCM interface operating as master, the stereo DAC operates at half the frequency of the clock at point B. This divided by two DAC clock is used as the source clock for the audio port.

The over sampling ratio of the ADC is set by ADC MODE (bit 0 of 0x07h)). The table below shows the required clock frequency at point **C** for the different ADC modes.

TABLE 5. Common ADC Clock Frequencies

ADC Sample Rate (kHz)	Clock Required at C (OSR = 125)	Clock Required at C (OSR = 128)
8	1 MHz	1.024 MHz
11.025	1.378125 MHz	1.4112 MHz
12	1.5 MHz	1.536 MHz
16	2 MHz	2.048 MHz
22.05	2.75625 MHz	2.8224 MHz
24	3 MHz	3.072 MHz

Methods for producing these clock frequencies are described in the PLL Section.

12.5 PLL M DIVIDER CONFIGURATION REGISTER

This register is used to control the input section of the PLL. (Note 12)

TABLE 6. PLL_M (0x02h)

Bits	Field	Descripti	ion	
0	RSVD	RESERVED		
6:0	PLL_M	PLL_M	Input Divider Value	
		0	No Divided Clock	
		1	1	
		2	1.5	
		3	2	
		4	2.5	
			3 to 63	
		126	63.5	
		127	64	
7	FORCERQ	If set, the R and Q divider are enabled and the DAC and ADC clocks are propagated. This allows operation of the I ² S and PCM interfaces without the ADC or DAC being enabled, for example to act as a bridge or a clock master.		

The M divider should be set such that the output of the divider is between 0.5 MHz and 5 MHz.

The division of the M divider is derived from PLL_M such that:

$M = (PLL_M + 1) / 2$

Note 12: See Further Notes on PLL Programming for more detail.

12.6 PLL N DIVIDER CONFIGURATION REGISTER

This register is used to control the feedback divider of the PLL. (Note 13)

Bits	Field	Description		
7:0	PLL_N	This programs the PLL feedback divider as follows:		
		PLL_N	Feedback Divider Value	
		0 to 10	10	
		11	11	
		12	12	
		13	13	
		14	14	
		249	249	
		250 to 255	250	

TABLE 7. PLL_N (0x03h)

The N divider should be set such that the output of the divider is between 0.5 MHz and 5 MHz. (Fin/M)*N will be the target resting VCO frequency, F_{VCO} . The N divider should be set such that 40 MHz < (Fin/M)*N < 60 MHz. Fin/M is often referred to as F_{comp} (comparison frequency) or F_{ref} (reference frequency), in this document F_{comp} is used.

The integer division of the N divider is derived from PLL_N such that:

For 9 < PLL_N < 251: N = PLL_N

Note 13: See Further Notes on PLL Programming for further details.

12.7 PLL P DIVIDER CONFIGURATION REGISTER

This register is used to control the output divider of the PLL. (Note 14)

Bits	Field	Description		
3:0	PLL_P	This programs the PLL output divider as follows:		
		PLL_P	Output Divider Value	
		0	No Divided Clock	
		1	1	
		2	1.5	
		3	2	
		4	2.5	
			3 to 7	
		14	7.5	
		15	8	
6:4	Q_DIV	This programs the Q Divider		
		Q_DIV	Divide Value	
		0002	2	
		0012	3	
		0102	4	
		0112	6	
		1002	8	
		101 ₂	10	
		1102	12	
		1112	13	
7	FAST_VCO	This programs the PLL VCO range:		
		FAST_VCO	PLL VCO Range	
		0	40 to 60MHz	
		1	60 to 80MHz	

TABLE 8. PLL_P (0x04h)

The division of the P divider is derived from PLL_P such that:

 $P = PLL_P + 1$

Note 14: See Further Notes on PLL Programming for more details.

12.8 PLL N MODULUS CONFIGURATION REGISTER

This register is used to control the modulation applied to the feedback divider of the PLL. (Note 15)

Bits	Field	Description		
4:0	PLL_N_MOD	This programs the PLL N divider's fractional compo	onent:	
		PLL_N_MOD	Fractional Addition	
		0	0/32	
		1	1/32	
		2 to 30	2/32 to 30/32	
		31	31/32	
6:5	PLL_CLK_SEL	This selects the clock to be used as input for the au	udio PLL.	
		PLL_IN	IPUT_CLK	
		002	MCLK	
		012	I2S_CLK_IN	
		102	PCM_CLK_IN	
		112	_	
7	RSVD	Reserved.	•	

TABLE 9. PLL_N_MOD (0x05h)

The complete N divider is a fractional divider as such:

$N = PLL_N + PLL_N_MOD/32$

If the modulus input is zero then the N divider is simply an integer N divider. The output from the PLL is determined by the following formula:

$$F_{out} = (F_{in}*N)/(M*P)$$

Note 15: See Further Notes on PLL Programming for more details.

12.9 FURTHER NOTES ON PLL PROGRAMMING

The sigma-delta PLL Is designed to drive audio circuits requiring accurate clock frequencies of up to 30MHz with frequency errors noise-shaped away from the audio band. The 5 bits of modulus control provide exact synchronization of 48kHz and 44.1kHz sample rates from any common system clock. In systems where an isochronous I²S data stream is the source of data to the DAC a clock synchronous to the sample rate should be used as input to the PLL (typically the I²S clock). If no isochronous source is available, then the PLL can be used to obtain a clock that is accurate to within 1Hz of the correct sample rate although this is highly unlikely to be a problem.

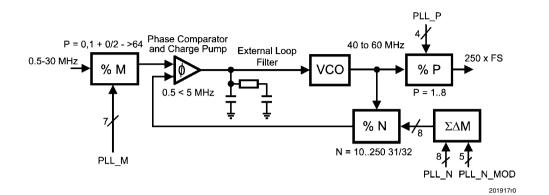


FIGURE 7. PLL Overview

TABLE 10. Example PLL Settings for 48 kHz and 44.1 kHz Sample Rates in DAC MODE 00

F _{in} (MHz)	F _s (kHz)	м	N	Р	PLL_M	PLL_N	PLL_N_MOD	PLL_P	F _{out} (MHz)
11	48	11	60	5	21	60	0	9	12
12.288	48	4	19.53125	5	7	19	17	9	12
13	48	13	60	5	25	60	0	9	12
14.4	48	9	37.5	5	17	37	16	9	12
16.2	48	27	100	5	53	100	0	9	12
16.8	48	14	50	5	27	50	0	9	12
19.2	48	13	40.625	5	25	40	20	9	12
19.44	48	27	100	6	53	100	0	11	12
19.68	48	20.5	62.5	5	40	62	16	9	12
19.8	48	16.5	50	5	32	50	0	9	12
11	44.1	11	55.125	5	21	55	4	9	11.025
11.2896	44.1	8	39.0625	5	15	39	2	9	11.025
12	44.1	5	22.96875	5	9	22	31	9	11.025
13	44.1	13	55.125	5	25	55	4	9	11.025
14.4	44.1	12	45.9375	5	23	45	30	9	11.025
16.2	44.1	9	30.625	5	17	9	20	9	11.025
16.8	44.1	17	55.78125	5	33	30	25	9	11.025
19.2	44.1	16	45.9375	5	31	45	30	9	11.025
19.44	44.1	13.5	38.28125	5	26	38	9	9	11.025
19.68	44.1	20.5	45.9375	44	40	45	30	7	11.025
19.8	44.1	11	30.625	5	21	30	20	9	11.025

F _{in} (MHz)	F _s (kHz)	м	Ν	Р	PLL_M	PLL_N	PLL_N_MOD	PLL_P	F _{out} (MHz)
12	48	12.5	64	5	24	64	0	9	12.288
13	48	26.5	112.71875	4.5	52	112	23	8	12.288
14.4	48	37.5	128	4	74	128	0	7	12.288
16.2	48	37.5	128	4.5	74	128	0	8	12.288
16.8	48	12.53	32	3.5	24	32	0	6	12.288
19.2	48	12.5	32	4	24	32	0	7	12.288
19.44	48	40.5	128	58	80	128	0	9	12.288
19.68	48	20.5	64	5	40	64	0	9	12.288
19.8	48	37.5	128	5.5	74	128	0	10	12.288
12	44.1	35.5	133.59375	4	70	133	19	7	11.2896
13	44.1	37	144.59375	4.5	73	144	19	8	11.2896
14.4	44.1	37.5	147	5	74	147	0	9	11.2896
16.2	44.1	47.5	182.0625	5.5	94	182	2	10	11.2896
16.8	44.1	12.5	42	5	24	42	0	9	11.2896
19.2	44.1	12.5	36.75	5	24	36	24	9	11.2896
19.44	44.1	37.5	98	4.5	74	98	0	9	11.2896
19.68	44.1	44.5	114.875	4.5	88	114	28	8	11.2896
19.8	44.1	48	136.84375	5	95	136	27	9	11.2896

These tables cover the most common applications, obtaining clocks for derivative sample rates such as 22.05 kHz should be done by increasing the P divider value or using the R/Q dividers.

An example of obtaining 12.000 MHz from 1.536 MHz is shown below (this is typical for deriving DAC clocks from I2S datastreams).

Choose a small range of P so that the VCO frequency is swept between 40 MHz and 60 MHz (or 60–80 MHz if VCOFAST is used). Remembering that the P divider can divide by half integers, for a 12 MHz output, this gives possible P values of 3, 3.5, 4, 4.5, or 5. The M divider should be set such that the comparison frequency (Fcomp) is between 0.5 and 5 MHz. This gives possible M values of 1, 1.5, 2, 2.5, or 3. The most accurate N and N_MOD can be calculated by sweeping the P and M inputs of the following formulas:

$N = FLOOR(((Fout/Fin)^{*}(P^{*}M)), 1)$

$N_MOD = ROUND(32^*(((Fout)/Fin)^*(P^*M)-N),0)$

This shows that setting M = 1, N = 39+1/16, P = 5 (i.e. PLL_M = 0, PLL_N = 39, PLL_N_MOD = 2, & PLL_P = 4) gives a comparison frequency of 1.536MHz, a VCO frequency of 60 MHz and an output frequency of 12.000 MHz. The same settings can be used to get 11.025 from 1.4112 MHz for 44.1 kHz sample rates.

Care must be taken when synchronization of isochronous data is not possible, i.e. when the PLL has to be used but an exact frequency match cannot be found. The I2S should be master on the LM49370 so that the data source can support appropriate SRC as required. This method should only be used with data being read on demand to eliminate sample rate mismatch problems.

Where a system clock exists at an integer multiple of the required ADC or DAC clock rate it is preferable to use this rather than the PLL. The LM49370 is designed to work in 8, 12, 16, 24, 48 kHz modes from a 12 MHz clock and 8 kHz modes from a 13 MHz clock without the use of the PLL. This saves power and reduces clock jitter which can affect SNR.

12.10 ADC_1 CONFIGURATION REGISTER

This register is used to control the LM49370's audio ADC.

TABLE 12. ADC_1 (0x06h)

Bits	Field	De	escription	
0	MIC_SELECT	If set the microphone preamp output is added to the ADC input signal.		
1	CPI_SELECT	If set the cell phone input is added to the ADC input signal.		
2	LEFT_SELECT	If set the left stereo bus is added to the ADC input signal.		
3	RIGHT SELECT	If set the right stereo bus is added to the ADC input signal.		
5:4	ADC_SAMPLE_	This programs the closest expected sample rate of the mono ADC, which is a variable required by the		
	RATE	AGC algorithm whenever the AGC is in use. This	s does not set the sample rate of the mono ADC.	
		ADC_SAMPLE_RATE	Sample Rate	
		002	8 kHz	
		012	12 kHz	
		102	16 kHz	
		112	24 kHz	
7:6	HPF_MODE	This sets the HPF of the ADC	•	
		HPF-MODE	HPF Response	
		002	No HPF	
		012	F _s = 8 kHz, –0.5 dB @ 300 Hz, Notch @ 55 Hz	
			F _S = 12 kHz, –0.5 dB @ 450 Hz, Notch @ 82 Hz	
			F _S = 16 kHz, –0.5 dB @ 600 Hz, Notch @ 110 Hz	
		10 ₂	F _S = 8 kHz, -0.5 dB @ 150 Hz, Notch @ 27 Hz	
			F _S = 12 kHz, –0.5 dB @ 225 Hz, Notch @ 41 Hz	
			F _S = 16 kHz, –0.5 dB @ 300 Hz, Notch @ 55 Hz	
		112	No HPF	

12.11 ADC_2 CONFIGURATION REGISTER

This register is used to control the LM49370's audio ADC.

		TABLE 13. ADC_2 (0x07h)	
Bit s	Field	Description		
0	ADC_MODE	This sets the oversampling ratio of the ADC		
		MODE	ADC OSR	
		0	125fs	
		1	128fs	
1	ADC_MUTE	If set, the analog inputs to the ADC are muted.		
4:2	AGC_FRAME_TIME	value of the AGC defined by AGC_TARGET (bits [3:1	rithm. In a given frame, the AGC's peak detector ne audio signal and compares this value to the target] of register (0x08h)) in order to adjust the microphone basically sets the sample rate of the AGC to adjust for	
		AGC_FRAME_TIME	Time (ms)	
		0002	96	
		0012	128	
		0102	192	
		0112	256	
		1002	384	
		1012	512	
		1102	768	
		1112	1000	
6:5	ADC_CLK	This selects the clock to be used by the audio ADC s	ystem.	
		ADC_CLK	Source	
		002	MCLK	
		012	PLL_OUTPUT	
		102	I2S_CLK_IN	
		112	PCM_CLK_IN	
7	NGZXDD	If set, the noise gate will not wait for a zero crossing ADC's HPF is disabled and if there is a large DC or lo	-	
		NGZXDD	Result	
		0	Noise Gate operates on ZXD events	
		1	Noise Gate operates on frame boundaries	

Note 16: Refer to the AGC overview for further detail.

12.12 AGC_1 CONFIGURATION REGISTER

This register is used to control the LM49370's Automatic Gain Control. (Note 17)

Bit s	Field	Description				
0	AGC_ENABLE	If set, the AGC controls the analog microphone preamplifier gain into the system. This feature is useful for microphone signals that are routed to the ADC.				
3:1	AGC_TARGET	This programs the target level of the AGC. This will depend on the expected transients and desired headroor Refer to AGC_TIGHT (bit 7 of 0x09h) for more detail.				
		AGC_TARGET	Target Level			
		0002	–6 dB			
		0012	–8 dB			
		0102	-10 dB			
		0112	–12 dB			
		1002	-14 dB			
		1012	–16 dB			
		1102	–18 dB			
		1112	–20 dB			
4	NOISE_GATE_ON	I If set, signals below the noise gate threshold are muted. The noise gate is only activated after a set period o signal absence.				
7:5	NOISE_ GATE_ THRES	This field sets the expected background noise level relative to the peak signal level. The sole pre- signals below this level will not result in an AGC gain change of the input and will be gated from output if the NOISE_GATE_ON is set. This level must be set even if the noise gate is not in use as it by the AGC algorithm.				
		NOISE_GATE_THRES	Level			
		0002	–72 dB			
		0012	–66 dB			
		0102	-60 dB			
		0112	–54 dB			
		1002	-48 dB			
		1012	-42 dB			
		1102	–36 dB			
		1112	–30 dB			

TABLE 14. AGC_1 (0x08h)

Note 17: See the AGC overview.

12.13 AGC_2 CONFIGURATION REGISTER

This register is used to control the LM49370's Automatic Gain Control.

TABLE 15. AGC_2 (0x09h)

Bits	Field		Description	
3:0	AGC_MAX_GAIN	This programs the maximum gain	that the AGC algorithm can apply to	o the microphone preamplifier.
		AGC_MAX_GAIN	Max Prean	nplifier Gain
		00002	6	dB
		00012	8	dB
		00102	10	dB
		00112	12	dB
		0100 ₂ to 1100 ₂	0100 ₂ to 1100 ₂ 14 dB to 30 dB	
		11012	32	dB
		11102	34	dB
		11112	36	dB
6:4	AGC_DECAY	This programs the speed at which	the AGC will increase gains if it det	ects the input level is a quiet signal
		AGC_DECAY	Step Ti	me (ms)
		0002	3	32
		0012	6	64
		0102	1.	28
		0112	2	56
		1002	5	12
		1012	1024	
		1102	2048	
		1112	4096	
7	AGC_TIGHT	If set, the AGC algorithm controls	algorithm controls the microphone preamplifier more exactly. (Note 18)	
	AGC_TIGHT = 0	AGC_TARGET	Min Level	Max Level
		0002	-6 dB	–3 dB
		0012	–8 dB	-4 dB
		0102	-10 dB	–5 dB
		0112	–12 dB	-6 dB
		1002	-14 dB	-7 dB
		1012	-16 dB	–8 dB
		1102	–18 dB	–9 dB
		1112	–20 dB	–10 dB
	AGC_TIGHT = 1	0002	-6 dB	–3 dB
		0012	-8 dB	–5 dB
		0102	–10 dB	–7 dB
		0112	–12 dB	–9 dB
		1002	–14 dB	–11 dB
		1012	-16 dB	–13 dB
		1102	–18 dB	–15 dB
		1112	–20 dB	–17 dB

Note 18: The AGC can be used to control the analog path of the microphone to the output stages or to optimize the microphone path for recording on the ADC. When the analog path is used this bit should be set to ensure the target is tightly adhered to. If the ADC is the only destination of the microphone or the desired analog mixer level is line level then AGC_TIGHT should be cleared, allowing greater dynamic rage of the recorded signal. For further details see the AGC overview.

12.14 AGC_3 CONFIGURATION REGISTER

This register is used to control the LM49370's Automatic Gain Control. (Note 19)

Bits	Field	Description			
4:0	AGC_HOLDTIME	This programs the amount of delay before the AGC algorithm begins to adjust the gain of the microphone preamplifier.			
		AGC_HOLDTIME	No. of speech segments		
		000002	0		
		000012	1		
		000102	2		
		000112	3		
		00100 ₂ to 11100 ₂	4 to 28		
		11101 ₂	29		
		111102	30		
		111112	31		
7:5	AGC_ATTACK	This programs the speed at which the AGC will reduce gains if it detects the input level is too la			
		AGC_ATTACK	Step Time (ms)		
		0002	32		
		0012	64		
		0102	128		
		0112	256		
		1002	512		
		1012	1024		
		1102	2048		
		1112	4096		

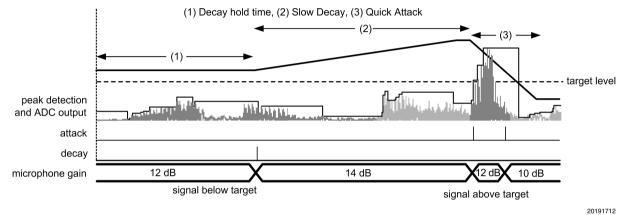
TABLE 16. AGC_3 (0x0Ah)

Note 19: See the AGC overview.

12.15 AGC OVERVIEW

The Automatic Gain Control (AGC) system can be used to optimize the dynamic range of the ADC for voice data when the level of the source is unknown. A target level for the output is set so that any transients on the input won't clip during normal operation. The AGC circuit then compares the output of the ADC to this level and increases or decreases the gain of the microphone preamplifier to compensate. If the audio from the microphone is to be output digitally through the ADC then the full dynamic range of the ADC can be used automatically. If the output is through the analog mixer then the ADC is used to monitor the microphone level. In this case, the analog dynamic range is less important than the absolute level, so *AGC_TIGHT* should be set to tie transients closely to the target level.

To ensure that the system doesn't reduce the quality of the speech by constantly modulating the microphone preamplifier gain, the ADC output is passed through an envelope detector. This frames the output of the ADC into time segments roughly equal to the phonemes found in speech (AGC_FRAME_TIME). To calculate this, the circuit must also know the sample rate of the data from the ADC (ADC_SAMPLERATE). If after a programmable number of these segments (AGC_HOLDTIME), the level is consistently below target, the gain will be increased at a programmable rate (AGC_DECAY). If the signal ever exceeds the target level (AGC_TARGET) then the gain of the microphone is reduced immediately at a programmable rate (AGC_ATTACK). This is demonstrated below:



AGC Operation Example

The signal in the above example starts with a small analog input which, after the hold time has timed out, triggers a rise in the gain $((1) \rightarrow (2))$. After some time the real analog input increases and it reaches the threshold for a gain reduction which decreases the gain at a faster rate $((2) \rightarrow (3))$ to allow the elimination of typical popping noises.

Only ADC outputs that are considered signal (rather than noise) are used to adjust the microphone preamplifier gain. The signal to noise ratio of the expected input signal is set by *NOISE_GATE_THRESHOLD*. In some situations it is preferable to remove audio considered to be consisting solely of background noise from the audio output; for example conference calls. This can be done by setting *NOISE_GATE_ON*. This does not affect the performance of the AGC algorithm.

The AGC algorithm should not be used where very large background noise is present. If the type of input data, application and microphone is known then the AGC will typically not be required for good performance, it is intended for use with inputs with a large dynamic range or unknown nominal level. When setting *NOISE_GATE_THRESHOLD* be aware that in some mobile phone scenarios the ADC SNR will be dictated by the microphone performance rather than the ADC or the signal. Gain changes to the microphone are performed on zero crossings. To eliminate DC offsets, wind noise, and pop sounds from the output of the ADC, the ADC's HPF should always be enabled.

12.16 MIC_1 CONFIGURATION REGISTER

This register is used to control the microphone configuration.

Bits	Field	Desc	ription			
3:0	PREAMP_GAIN	This programs the gain applied to the microphone p	reamplifier if the AGC is not in use.			
		PREAMP_GAIN	Gain			
		00002	6 dB			
		00012	8 dB			
		00102	10 dB			
		00112	12 dB			
		0100 ₂ to 1100 ₂	14 dB to 30 dB			
		11012	32 dB			
		11102	34 dB			
		11112	36 dB			
4	MIC_MUTE	If set, the microphone preamplifier is muted.	·			
5	INT_SE_DIFF	If set, the internal microphone is assumed to be sing	gle ended and the negative connection is connected			
		to the ADC common mode point internally. This allows a single-ended internal microphone to be used.				
6	INT_EXT	If set, the single ended external microphone is used and the negative microphone input is grounded internally, otherwise internal microphone operation is assumed. (Note 20)				

TABLE 17. MIC_1 (0x0Bh)

Note 20: On changing INT_EXT from internal to external note that the dc blocking cap will not be charged so some time should be taken (300 ms for a 1 µF cap) between the detection of an external headset and the switching of the output stages and ADC to that input to allow the DC points on either side of this cap to stabilize. This can be accomplished by deselecting the microphone input from the audio outputs and ADC until the DC points stabilize.

An active MIC path to CPOUT or the ADC may result in the microphone DC blocking caps causing audio pops under the following situations:

1) Switching between internal and external microphone operation while in chip modes '10' or '11'.

2) Toggling in and out of powerdown/standby modes.

3) Toggling between chip modes '10' and '11' whenever external microphone operation is selected.

4) The insertion/removal of a headset while in chip modes '10' or '11' whenever external microphone operation is selected.

To avoid these potential pop issues, it is recommended to deselect the microphone input from CPOUT and ADC until the DC points stabilize.

12.17 MIC_2 CONFIGURATION REGISTER

This register is used to control the microphone configuration.

TABLE 18. MIC_2 (0x0Ch)

Bits	Field		Description	
0	OCL_	This selects the voltage used as virtual ground (HP_VMID pin) in OCL mode. This will depend on the		
	VCM_ VOLTAGE	available supply and the power output requirements of the headphone amplifiers.		
		OCL_VCM_VOLTAGE	Volt	age
		0	1.2	2V
		1	1.	5V
2:1	MIC_ BIAS_ VOLTAGE	at once depending on the INT_EXT should be set to '11' only if A_V_{DD}	nce to the internal and external micro bit setting found in the MIC_1 (0x0 > 3.4V. In OCL mode, MIC_BIAS_V EXT_BIAS supply for a cellular he	Bh) register. MIC_BIAS_VOLTAC OLTAGE = '00' (EXT_BIAS = 2.0
		MIC_BIAS_VOLTAGE	EXT_BIAS	/INT_BIAS
		002	2.0	V
		012	2.!	5V
		102	2.8	3V
		112	3.3	3V
3	BUTTON_TYPE	If set, the LM49370 assumes that the button (if used) in the headset is in series (series push button) w the microphone, opening the circuit when pressed. The default is for the button to be in parallel (paralle push button), shorting out the microphone when pressed.		
5:4	BUTTON_	This sets the time used for debound	cing the pushing of the button on a h	neadset with a parallel push butte
	DEBOUNCE_	BUTTON_DEB	OUNCE_TIME	Time (ms)
	TIME	00	D ₂	0
		0.	12	8
		10) ₂	16
			1 ₂	32

In OCL mode there is a trade-off between the external microphone supply voltage (EXT_MIC_BIAS - OCL_VCM_ VOLTAGE) and the maximum output power possible from the headphones. A lower OCL_VCM_VOLTAGE gives a higher microphone supply voltage but a lower maximum output power from the headphone amplifiers due to the lower OCL_VCM_VOLTAGE - A_V_{SS}.

Available	Recommended	Supply to Microphone		
A_V_{DD}	EXT_MIC_BIAS	OCL_VCM_VOLT = 1.5V	OCL_VCM_VOLT = 1.2V	
> 3.4V	3.3V	1.8V	2.1V	
2.9V to 3.4V	2.8V	1.3V	1.6V	
2.8V to 2.9V	2.5V	1.0V	1.3V	
2.7V to 2.8V	2.5V	-	1.3V	

12.18 SIDETONE ATTENUATION REGISTER

This register is used to control the analog sidetone attenuation. (Note 21)

Bits Field Description 3:0 SIDETONE_ This programs the attenuation applied to the microphone preamp output to produce a sidetone signal. ATTEN SIDETONE_ATTEN Attenuation 00002 -Inf -30 dB 00012 00102 -27 dB 0011₂ –24 dB 01002 -21 dB 0101₂ to 1010₂ -18 dB to -3 dB 1011, to 1111, 0 dB

TABLE 20. SIDETONE (0x0Dh)

Note 21: An active SIDETONE path to an audio output may result in the microphone DC blocking caps causing audio pops under the following situations:

1) Switching between internal and external microphone operation while in chip modes '10' or '11'.

2) Toggling in and out of powerdown/standby modes.

3) Toggling between chip modes '10' and '11' whenever external microphone operation is selected.

4) The insertion/removal of a headset while in chip modes '10' or '11' whenever external microphone operation is selected.

To avoid potential pop noises, it is recommended to set SIDETONE_ATTEN to '0000' until DC points have stabilized whenever the SIDETONE path is used.

12.19 CP_INPUT CONFIGURATION REGISTER

This register is used to control the differential cell phone input.

TABLE 21. CP_INPUT (0x0Eh)

Bits	Field	Description	
4:0	CPI_LEVEL	This programs the gain/attenuation applied to the cell phone input.	
		CPI_LEVEL	Level
		000002	–34.5 dB
		000012	–33 dB
		000102	–31.5 dB
		000112	-30 dB
		00100 to 11100 ₂	–28.5 dB to +7.5 dB
		111012	+9 dB
		11110 ₂	+10.5 dB
		111112	+12 dB
5	CPI_MUTE	If set, the CPI input is muted at source.	•

12.20 AUX_LEFT CONFIGURATION REGISTER

This register is used to control the left aux analog input.

TABLE 22. AUX_LEFT (0x0Fh)

Bits	Field		Description	
4:0	AUX_	This programs the gain/attenuation applied to the AUX LEFT analog input to the mixer. (Note 22)		
	LEFT_	AUX_LEFT_LEVEL	Level (With Boost)	Level (Without Boost)
	LEVEL	000002	–34.5 dB	-46.5 dB
		000012	–33 dB	–45 dB
		00010 ₂	–31.5 dB	-43.5 dB
		000112	–30 dB	-42 dB
		00100 to 11100 ₂	–28.5 dB to +7.5 dB	-40.5 dB to -4.5 dB
		11101 ₂	+9 dB	–3 dB
		111102	+10.5 dB	–1.5 dB
		111112	+12 dB	0 dB
5	5 AUX_ If set, the gain of the AUX_LEFT input to the mixer is increased by 12 dB (see abo		dB (see above).	
	LEFT_	_		
	BOOST			
6	AUX_L_MUTE	If set, the AUX LEFT input is muted	d.	
7	AUX_OR_DAC_L	If set, the AUX LEFT input is passed to the mixer, the default is for the DAC LEFT output to be passed to		

Note 22: The recommended mixer level is 1V RMS. The auxiliary analog inputs can be boosted by 12 dB if enough headroom is available. Clipping may occur if the analog power supply is insufficient to cater for the required gain.

12.21 AUX_RIGHT CONFIGURATION REGISTER

This register is used to control the right aux analog input.

the mixer.

TABLE 23. AUX_RIGHT (0x10h) Bits Field Description 4:0 AUX_ This programs the gain/attenuation applied to the AUX RIGHT analog input to the mixer. (Note 23) RIGHT AUX RIGHT LEVEL Level (With Boost) Level (Without Boost) LEVEL 000002 -34.5 dB -46.5 dB -33 dB –45 dB 000012 -43.5 dB 00010, -31.5 dB 00011 -30 dB -42 dB -28.5 dB to +7.5 dB -40.5 dB to -4.5 dB 00100 to 11100₂ –3 dB 11101, +9 dB 11110, +10.5 dB -1.5 dB +12 dB 0 dB 11111, 5 AUX_ If set, the gain of the AUX_RIGHT input to the mixer is increased by 12 dB (see above). **RIGHT_BOOST** 6 AUX_R_MUTE If set, the AUX RIGHT input is muted. If set, the AUX RIGHT input is passed to the mixer, the default is for the DAC RIGHT output to be passed 7 AUX_OR_DAC_R to the mixer.

Note 23: The recommended mixer level is 1V RMS. The auxiliary analog inputs can be boosted by 12 dB if enough headroom is available. Clipping may occur if the analog power supply is insufficient to cater for the required gain.

12.22 DAC CONFIGURATION REGISTER

This register is used to control the DAC levels to the mixer.

Bits	Field		Description	
4:0	DAC_LEVEL	This programs the gain/attenuation applied to the DAC input to the mixer. (Note 24)		
		DAC_LEVEL	Level (With Boost)	Level (Without Boost)
		000002	–34.5 dB	–46.5 dB
		000012	–33 dB	–45 dB
		000102	–31.5 dB	-43.5 dB
		000112	–30 dB	-42 dB
		00100 to 11100 ₂	–28.5 dB to +7.5 dB	-40.5 dB to -4.5 dB
		111012	+9 dB	–3 dB
		111102	+10.5 dB	–1.5 dB
		111112	+12 dB	0 dB
5	DAC_BOOST	If set, the gain of the DAC inputs to	the mixer is increased by 12dB (se	ee above).
6	DAC_MUTE	If set, the stereo DAC input is muted on the next zero crossing.		
7	USE_AUX_ LEVELS	If set, the gain of the DAC inputs is controlled by the AUX_LEFT and AUX_RIGHT registers, allowing a stereo balance to be applied.		

TABLE 24. DAC (0x11h)

Note 24: The output from the DAC is 1V RMS for a full scale digital input. This can be boosted by 12 dB if enough headroom is available. Clipping may occur if the analog power supply is insufficient to cater for the required gain.

12.23 CP_OUTPUT CONFIGURATION REGISTER

This register is used to control the differential cell phone output. (Note 25)

TABLE 25. CP_OUTPUT (0x12h)

Bit	Field	Description	
S			
0	MIC_SELECT	f set, the microphone channel of the mixer is added to the CP_OUT output signal.	
1	RIGHT_SELECT	i set, the right channel of the mixer is added to the CP_OUT output signal.	
2	LEFT_SELECT	If set, the left channel of the mixer is added to the CP_OUT output signal.	
3	CPO_MUTE	If set, the CPOUT output is muted.	
4	MIC_NOISE_GAT	If this is set and NOISE_GATE_ON (register 0x08h) is enabled, the MIC to CPO path will be gated if the	
	E	signal is determined to be noise by the AGC (that is, if the signal is below the set noise threshold).	

Note 25: The gain of cell phone output amplifier is 0 dB.

12.24 AUX_OUTPUT CONFIGURATION REGISTER

This register is used to control the differential auxiliary output. (Note 26)

TABLE 26. AUX_OUTPUT (0x13h)

Bits	Field	Description	
0	CPI_SELECT	f set, the cell phone input channel of the mixer is added to the AUX_OUT output signal.	
1	RIGHT_SELECT	f set, the right channel of the mixer is added to the AUX_OUT output signal.	
2	LEFT_SELECT	f set, the left channel of the mixer is added to the AUX_OUT output signal.	
3	AUX_MUTE	_MUTE If set, the AUX_OUT output is muted.	

Note 26: The gain of the auxiliary output amplifier is 0 dB. If a second (external) loudspeaker amplifier is to be used its gain should be set to 12 dB to match the onboard loudspeaker amplifier gain.

12.25 LS_OUTPUT CONFIGURATION REGISTER

This register is used to control the loudspeaker output. (Note 27)

TABLE 27. LS_OUTPUT (0x14h)

Bits	Field	Description	
0	CPI_SELECT	f set, the cell phone input channel of the mixer is added to the loudspeaker output signal.	
1	RIGHT_SELECT	set, the right channel of the mixer is added to the loudspeaker output signal.	
2	LEFT_SELECT	f set, the left channel of the mixer is added to the loudspeaker output signal.	
3	LS_MUTE	If set, the loudspeaker output is muted.	
4	RSVD	Reserved.	

Note 27: The gain of the loudspeaker output amplifier is 12 dB.

12.26 HP_OUTPUT CONFIGURATION REGISTER

This register is used to control the stereo headphone output. (Note 28)

TABLE 28. HP_OUTPUT (0x15h)

Bits	Field	Description	
0	SIDETONE_SELECT	If set, the sidetone channel of the mixer is added to both of the headphone output signals.	
1	CPI_SELECT	If set, the cell phone input channel of the mixer is added to both of the headphone output signals.	
2	RIGHT_SELECT	If set, the right channel of the mixer is added to the headphone output. If the STEREO bit (0x00h) is set, the right channel is added to the right headphone output signal only. If the STEREO bit (0x00h) is cleared, it is added to both the right and left headphone output signals.	
3	LEFT_SELECT	If set, the left channel of the mixer is added to the headphone output. If the STEREO bit (0x00h) is set, the left channel is added to the left headphone output signal only. If the STEREO bit (0x00h) is cleared, it is added to both the right and left headphone output signals.	
4	HP_MUTE	If set, the headphone output is muted.	
5	STEREO	If set, the mixers assume that the signals on the left and right internal busses are highly correlated and when these signals are combined their levels are reduced by 6dB to allow enough headroom for them to be summed.	
6	OCL	If set, the part is placed in OCL (Output Capacitor Less) mode.	

Note 28: The gain of the headphone output amplifier is -6 dB for the cell phone input channel and sidetone channel of the mixer. When the STEREO bit (0x00h) is set, headphone output amplifier gain is -6 dB for the left and right channel. When the STEREO bit (0x00h) is cleared, the headphone output amplifier gain is -12 dB for the left and right channel for adding them and routing them to both headphone amplifiers).

12.27 EP_OUTPUT CONFIGURATION REGISTER

This register is used to control the mono earpiece output. (Note 29)

TABLE 29. EP_OUTPUT (0x16h)

Bits	Field	Description	
0	SIDETONE_SELECT	If set, the sidetone channel of the mixer is added to the earpiece output signal.	
1	CPI_SELECT	f set, the cell phone input channel of the mixer is added to the earpiece output signal.	
2	RIGHT_SELECT	If set, the right channel of the mixer is added to the earpiece output signal.	
3	LEFT_SELECT	If set, the left channel of the mixer is added to the earpiece output signal.	
4	EP_MUTE	If set, the earpiece output is muted.	

Note 29: The gain of the earpiece output amplifier is 6 dB.

12.28 DETECT CONFIGURATION REGISTER

This register is used to control the headset detection system.

TABLE 30. DETECT (0x17h)

Bits	Field	Desci	ription
0	DET_INT	If set, an IRQ is raised when a change is detected in that has been triggered by the headset detect.	the headset status. Clearing this bit will clear an \ensuremath{IRQ}
1	BTN_INT		essed. Clearing this hit will clear an IBO that has been
'		If set, an IRQ is raised when the headset button is pressed. Clearing this bit will clear an IRQ that has been triggered by a button event.	
2	TEMP_INT	If set, an IRQ is raised during a temperature event. The LM49370 will still automatically cycle the class AB power amplifiers off if the internal temperature is too high. This bit should not be set whenever the class D amplifier is turned on. Clearing this bit will clear an IRQ that has been triggered by a temperature event.	
6:3	HS_ DBNC_TIME	This sets the time used for debouncing the analog s insertion/removal of a headset.	ignals from the detection inputs used to sense the
		HS_DBNC_TIME	Time (ms)
		00002	0
		00012	8
		00102	16
		00112	32
		01002	48
		01012	64
		01102	96
		01112	128
		10002	192
		10012	256
		10102	384
		10112	512
		11002	768
		11012	1024
		11102	1536
		11112	2048

12.29 HEADSET DETECT OVERVIEW

The LM49370 has built in monitors to automatically detect headset insertion or removal. The detection scheme can differentiate between mono, stereo, mono-cellular and stereo-cellular headsets. Upon detection of headset insertion or removal, the LM49370 updates read-only bit 0 - headset absence/presence, bit 1- mono/stereo headset and bit 2 - headset without mic / with mic, of the STATUS register (0x18h). Headset insertion/removal and headset type can also be detected in standby mode; this consumes no analog supply current when the headset is absent.

The LM49370 can be programmed to raise an interrupt (set the IRQ pin high) when headset insert/removal is sensed by setting bit 0 of DETECT (0x17h). When headset detection is enabled in active mode and a headset is not detected, the HPL_OUT and HPR_OUT amplifiers will be disabled (switched off for capless mode and muted for AC-coupled mode) and the EXT_BIAS pin will be disconnected from the MIC_BIAS amplifier, irrespective of control register settings.

The LM49370 also has the capability to detect button press, when a button is present on the headset microphone. Both parallel button-type (in parallel with the headset microphone, default value) and series button-type (in series with the headset microphone) can be detected; the button type used needs to be defined in bit 3 of MIC_2 (0x0Ch). Button press can also be detected in standby mode; this consumes 10 μ A of analog supply current for a series type push button and 100 μ A for a parallel type push button. Upon button press, the LM49370 updates bit 3 of STATUS (0x18h). In active OCL mode, with internal microphone selected (INT_EXT = 0; (reg 0x0Bh)), if a parallel pushbutton headset is inserted into the system, INT_EXT must be set high before BTN (bit 3 of STATUS (0x18h)) can be read. The LM49370 can also be programmed to raise an interrupt on the IRQ pin when button press is sensed by setting bit 1 of DETECT (0x17h).

The LM49370 provides debounce programmability for headset and button detect. Debounce programmability can be used to reject glitches generated, and hence avoid false detection, while inserting/removing a headset or pressing a button.

Headset insert/removal debounce time is defined by HS_DBNC_TIME; bits 6:3 of DETECT (0x17h). Parallel button press debounce time is defined by BTN_DBNC_TIME; bits 5:4 of MIC_2 (0x0Ch).

Note that since the first effect of a series button press (microphone disconnected) is indistinguishable from headset removal, the debounce time for series button press in defined by HS_DBNC_TIME.

Headset and push button detection can be enabled by setting CHIP_MODE 0; bit 0 of BASIC (0x00h). For reliable headset / push button detection all following bits should be defined before enabling the headset detection system:

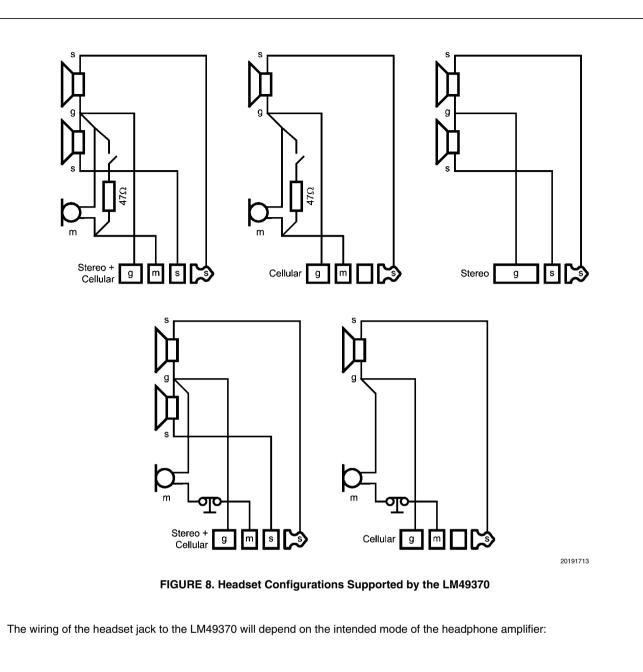
1) the OCL-bit (AC-Coupled / Capless headphone interface (bit 6 of HP_OUTPUT (0x15h))

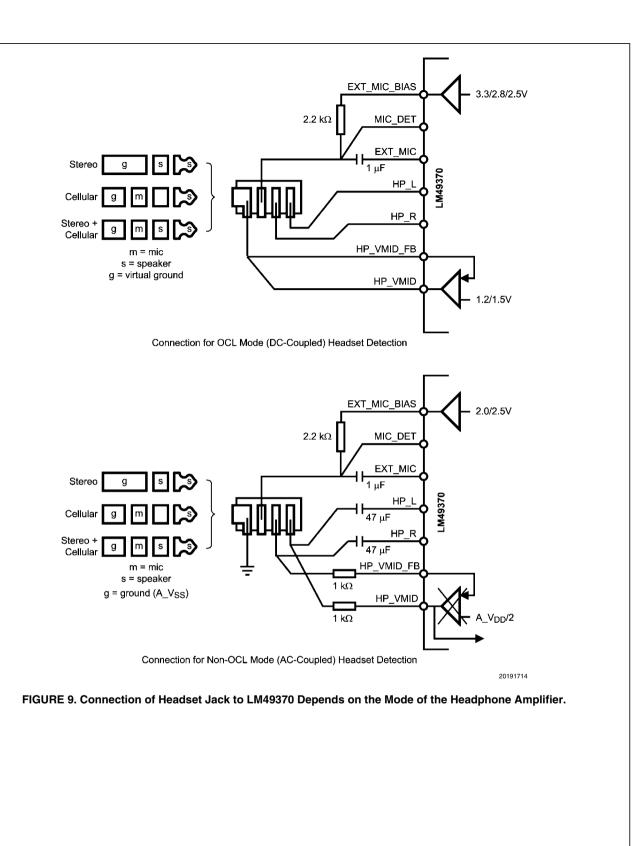
2) the headset insert/removal debounce settings (bit 6:3 of DETECT (0x17h))

3) the BTN_TYPE-bit (Parallel / Series push button type (bit 3 of MIC_2 (0x0Ch))

4) the parallel push button debounce settings (bit 5:4 of MIC_2 (0x0Ch))

Figure 8 shows terminal connections and jack configuration for various headsets. Care should be taken to avoid any DC path from the MIC_DET pin to ground when a headset is not inserted.





12.30 STATUS REGISTER

This register is used to report the status of the device.

TABLE 31. STATUS (0x18h)

Bits	Field	Description	
0	HEADSET	This field is high when headset presence is detected (only valid if the detection system is enabled). (Note	
		30)	
1	STEREO_	This field is high when a headset with stereo speakers is detected (only valid if the detection system is	
	HEADSET	enabled). (Note 30)	
2	MIC	This field is high when a headset with a microphone is detected (only valid if the detection system is	
		enabled). (Note 30)	
3	BTN	This field is high when the button on the headset is pressed (only valid if the detection system is enabled).	
		IRQ is cleared when the button has been released and this register has been written to. (Note 31)	
4	TEMP	this field is high then a temperature event has occurred (write to this register to clear IRQ). This field	
		stay high even when the IRQ is cleared so long as the event occurs. This bit is only valid whenever the	
		loudspeaker amplifier is turned off. (Note 31)	
5	GPIN1	When GPIO_SEL is set to a readable configuration a digital input on GPIO1 can be read back here.	
6	GPIN2	When GPIO_SEL is set to a readable configuration, a digital input on the relevant GPIO can be read back	
		here.	

Note 30: The detection IRQ is cleared when this register has been written to.

Note 31: This field is cleared whenever the STATUS (0x18h) register has been written to.

12.31 3D CONFIGURATION REGISTER

This register is used to control the configuration of the 3D circuit.

TABLE 32. 3D (0x19h)

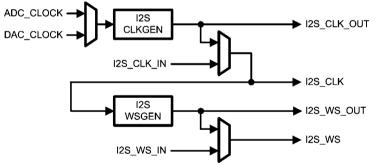
Bits	Field	Description			
0	3D_ENB	Setting this bit enables the 3D effect. When cleared to zero, the 3D effect is disabled and the 3D module then passes the I ² S left and right channel inputs to the DAC unchanged. The stereo AUX inputs are unaffected by the 3D module.			
1	3D_TYPE	and setting it to one se Type1: Rout = Ri-G*Lo	but3d, Lout = Li-G*Rout3d .out3d, Lout = Li+G*Rout3d input		
		Rout3d = Ri filtered th	rough a high-pass filter with a corner frequency controlled by FREQ ough a high-pass filter with a corner frequency controlled by FREQ		
3:2	LEVEL	This programs the leve	el of 3D effect that is applied.		
			LEVEL		
		002	25%		
		012	37.5%		
		10 ₂	50%		
		11 ₂	75%		
5:4	FREQ	This programs the HP	F rolloff (-3dB) frequency of the 3D effect.		
			FREQ		
		002	0Hz		
		012	300Hz		
		10 ₂	600Hz		
		11 ₂	900Hz		
6	ATTENUATE	bit to one attenuates the this may be appropriated adding the same polar	o maintains the level of the left and right input channels at the output. Setting this he output level by 50%. It for high level audio inputs when type 2 3D effect is used. Type 2 effect involves rity of left and right inputs to give the final outputs. Type 2 effect has the potential condition, however this bit offers an alternative to clipping.		
7	CUST_COMP		nsation filter may be programmed by the user through registers (0x20h) to(0x25h).		

12.32 I2S PORT MODE CONFIGURATION REGISTER

This register is used to control the audio data interfaces.

TABLE 33. I2S Mode (0x1Ah)

Bits	Field		Description	
0	I2S_OUT_ENB	If set, the I2S outpu	t bus is enabled. If cleared, the I2S output will be tristate and all RX clocks will be	
		gated.		
1	I2S_IN_ENB	If set, the I2S input	is enabled. If this bit cleared, the I ² S input is ignored and all TX clocks gated.	
2	I2S_MODE	This programs the	format of the I ² S interface.	
			Definition	
		0	Normal	
		1	Left Justified	
3 I2S_STEREO_REVERSE		If set, the left and ri	ight channels are reversed.	
			Operation	
		0	Normal	
		1	Reversed	
4	I2S_WS_MS	If set, I2S_WS generation is enabled and is Master. If cleared, I2S_WS acts as slave.		
6:5	I2S_WS_GEN_MODE	This programs the	I ² S word length.	
			Bits/Word	
		002	16	
		012	25	
		10 ₂	32	
		11 ₂	_	
7	I2S_WORD_ORDER	This bit alters the F is set: left then righ	X phasing of left and right channels. If this bit is cleared: right then left. If this b t.	



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I2S Audio Port CLOCK/SYNC Options

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12.33 I2S PORT CLOCK CONFIGURATION REGISTER

This register is used to control the audio data interfaces.

TABLE 34. I2S Clock (0x1Bh)

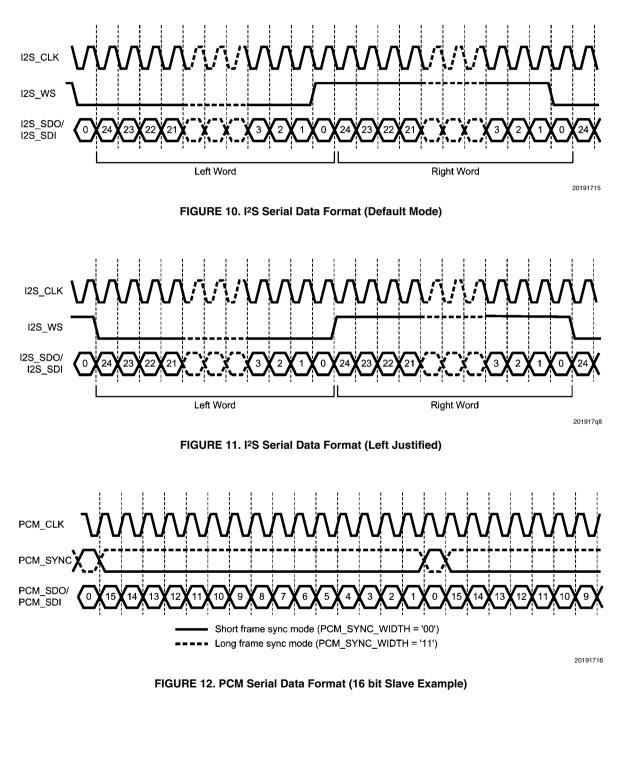
		TABLE 04. 120 (
Bit	Field		Description	
<u>s</u>				
0	I2S_CLOCK_MS	_	enabled and is Master. If t	his bit is cleared, then the I2S clock is
<u> </u>		driven by the device slave.		
1	I2S_CLOCK_SOURCE	This selects the source of the cloc		-
		I2S_CLOCK_SOURCE		ck is source from
		0		C (from R divider)
		1		C (from Q divider)
5:2	I2S_CLOCK_GEN_MODE	clock is used to generate I2S_CL		by I2S_CLOCK_SOURCE. This divided 2)
		Value	Divide By	Ratio
		00002	1	
		00012	2	
		00102	4	
		00112	6	
		01002	8	
		01012	10	
		01102	16	
		01112	20	_
		1000 ₂	2.5	2/5
		1001 ₂	3	1/3
		1010 ₂	3.90625	32/125
		1011 ₂	5	25/125
		1100 ₂	7.8125	16/125
		1101 ₂	—	—
		1110 ₂	_	_
		11112	_	_
7:6	PCM_SYNC_WIDTH	This programs the width of the PC		
			Genera	ted SYNC Looks like:
		002	1 bit (Used	d for Short PCM Modes)
		012	4 bits (Use	d for Long PCM Modes)
		102	8 bits (Use	d for Long PCM Modes)
		112		ed for Long PCM Modes)
			Should not be set	if the bits/word is less than 16.

Note 32: For DAC_MODE = '00', '10', '11', DAC_CLOCK is the clock at the output of the R divider. For DAC_MODE = '01', DAC_CLOCK is a divided by two version of the clock at the output of the R divider.

12.34 DIGITAL AUDIO DATA FORMATS

I²S master mode can only be used when the DAC is enabled unless the FORCE_RQ bit is set. PCM Master mode can only be used when the ADC is enabled, unless the FORCE_RQ bit is set. If the PCM receiver interface is operated in slave mode the clock and sync should be enabled at the same time because the PCM receiver uses the first PCM frame to calculate the PCM interface format. This format can not be changed unless a soft reset is issued. Operating the LM49370 in master mode eliminates the risk of sample rate mismatch between the data converters and the audio interfaces.

In slave mode, the PCM and I²S receivers only record the 1st 16 and 18 bits of the serial words respectively. The I²S and PCM formats are as followed:



12.35 PCM PORT MODE CONFIGURATION REGISTER

This register is used to control the audio data interfaces.

TABLE 35. PCM MODE (0x1Ch)

Bits	Field	Description		
0	PCM_OUT_ENB	If set, the PCM output bus is enal	bled. If this bit is cleared, thr PCM output will be tristate and all	
		RX clocks will be gated.		
1	PCM_IN_ENB	If set, the PCM input is enabled. I	f this bit is cleared, the PCM input is ignored and TX clocks are	
		generated.		
3	PCM_CLOCK_SOURCE	DAC or ADC Clock 0 = DAC, 1 = ADC (Note 32)		
4	PCM_SYNC_MS	If set, PCM_SYNC generation is enabled and is driven by the device (Master).		
5	PCM_SDO_LSB_HZ	If set, when the PCM port has run out of bits to transmit, it will tristate the SDO output.		
6	PCM_COMPAND	If set, the data sent to the PCM port is companded and the PCM data received by the PCM receive		
		is treated as companded data.		
7	PCM_ALAW_µLAW	If PCM_ COMPAND is set, then the data across the PCM interface to the DAC and from the A		
		is companded as follows:		
		PCM_ALAW_µLAW Commanding Type		
		0 µ-LAW		
		1	A-Law	

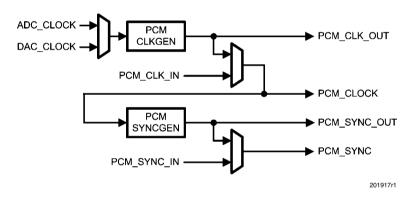


FIGURE 13. PCM Audio Port CLOCK/SYNC Options

12.36 PCM PORT CLOCK CONFIGURATION REGISTER

This register is used to control the configuration of audio data interfaces.

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TABLE 36. PCM Clock (0x1Dh)

Bits	Field		Description				
3:0	PCM_CLOCK_	This programs a clock divider tha					
	GEN_MODE	(0x1Ch). The divided clock is use	(0x1Ch). The divided clock is used to generate PCM_CLK in Master mode. (Note 32)				
		Value	Divide By	Ratio			
		00002	1				
		00012	2				
		00102	4				
		00112	6				
		01002	8				
		01012	10				
		01102	16				
		01112	20	_			
		10002	2.5	2/5			
		10012	3	1/3			
		10102	3.90625	32/125			
		10112	5	25/125			
		1100 ₂	7.8125	16/125			
		1101 ₂	_	_			
		1110 ₂	_	_			
		1111 ₂	_	_			
6:4	PCM_SYNC_MODE	This programs a clock divider tha PCM_SYNC.	t divides PCM_CLK. The divided	I clock is used to generate			
		Valve	Divi	de By			
		0002		8			
		0012	1	16			
		0102	2	25			
		0112	3	32			
		1002	6	64			
		1012	1	28			
		1102	-	_			
		1112	-	_			

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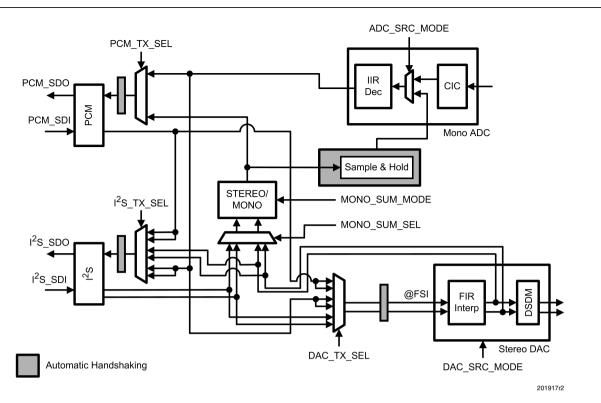
12.37 SRC CONFIGURATION REGISTER

This register is used to control the configuration of the Digital Routing interfaces. (Note 33)

Bits Field Description 0 PCM_TX_SEL This controls the data sent to the PCM transmitter. PCM_TX_SEL Source 0 ADC 1 MONO SUM Circuit This controls the data sent to the I²S transmitter. 2:1 I2S_TX_SEL 12S_TX_SEL Source ADC 002 01₂ PCM Receiver 10₂ DAC Interpolator (oversampled) 11, Disabled DAC_INPUT_SEL This controls the data sent to the DAC. 4:3 DAC_INPUT_SEL Source I2S Receiver (In stereo) 002 012 PCM Receiver (Dual Mono) 10₂ ADC Disabled 11₂ 5 MONO_SUM_SEL This controls the data sent to the Stereo to Mono Converter MONO_SUM_SEL Source DAC Interpolated Output 0 **I2S Receiver Output** 1 7:6 MONO_SUM_MODE This controls the operation of the Stereo to Mono Converter. MONO_SUM_ MODE Operation 00₂ (Left + Right)/2 012 Left 10₂ Right 11₂ (Left + Right)/2

TABLE 37. Bridges (0x1Eh)

Note 33: Please refer to the Application Note AN-1591 for the detailed discussion on how to use the I2S to PCM Bridge.





12.38 GPIO CONFIGURATION REGISTER

This register is used to control the GPIOs and to control the digital signal routing when using the ADC and DAC to perform sample rate conversion.

Bits	Field	Description				
2:0	GPIO_1_SEL	This configures the GPIO_1 pin.				
		GPIO_1_SEL	Does What?	Direction		
		0002	Disable	HiZ		
		0012	SPI_SDO	Output		
		0102	Output 0	Output		
		0112	Output 1	Output		
		1002	Read	Input		
		1012	Class D Enable	Output		
		1102	AUX Enable	Output		
		1112	Dig_Mic_Data	Input		
5:3	GPIO_2_SEL	This configures the GPIO_2 pin.				
		GPIO_2_SEL	Does What?	Direction		
		0002	Disable	HiZ		
		0012	SPI_SDO	Output		
		0102	Output 0	Output		
		0112	Output 1	Output		
		1002	Read	Input		
		1012	Class D Enable	Output		
		110 ₂	Dig_Mic L Clock	Output		
		111 ₂	Dig_Mic R Clock	Output		
6	ADC_SRC_MODE	If set, the ADC analog is disabled a	and the digital is enabled, using the	e resampler input.		
7	DAC_SRC_MODE	This does not have to be set to use DAC analog to save power.	DAC in SRC mode, but should be	set if the user wishes to disable the		

TABLE 38. GPIO Control (0x1Fh)

12.39 DAC PATH COMPENSATION FIR CONFIGURATION REGISTERS

To allow for compensation of roll off in the DAC and analog filter sections an FIR compensation filter is applied to the DAC input data at the original sample rate. Since the DAC can operate at different over sampling ratios the FIR compensation filter is programmable. By default the filter applies approx 2dB of compensation at 20kHz. 5 taps is sufficient to allow passband equalization and ripple cancellation to around +/0.01dB.

The filter can also be used for precise digital gain and simple tone controls although a DSP or CPU should be used for more powerful tone control if required. As the FIR filter must always be phase linear, the coefficients are symmetrical. Coefficients C0, C1, and C2 are programmable, C3 is equal to C1 and C4 is equal to C0. The maximum power of this filter must not exceed that of the examples given below:

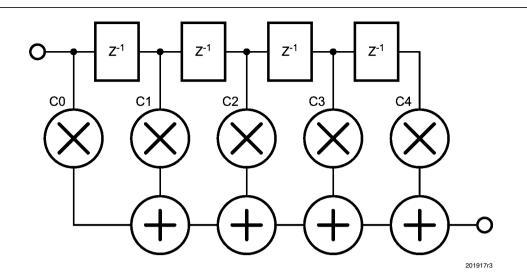


FIGURE 15. FIR Consumption Filter Taps

Sample Rate	DAC_MODE	C0	C1	C2	C3	C4
48kHz	00	334	-2291	26984	-2291	343
48kHz	01	61	-371	25699	-371	61

For DAC_MODE = '00 and '01', the defaults should be sufficient; but for DAC_MODE = '10' and '11', care should be taken to ensure the widest bandwidth is available without requiring such a large attenuation at DC that inband noise becomes audible.

TABLE 39. Compensation Filter C0 LSBs (0x20h)

	•		
Bits	Field	Description	
7:0	C0_LSB	Bits 7:0 of C0[15:0]	
	т	ABLE 40. Compensation Filter C0 MSBs (0x21h)	
Bits	Field	Description	
7:0	C0_MSB	Bits 15:8 of C0[15:0]	
	т	ABLE 41. Compensation Filter C1 LSBs (0x22h)	
Bits	Field	Description	
7:0	C1_LSB	Bits 7:0 of C1[15:0]	
	Т	ABLE 42. Compensation Filter C1 MSBs (0x23h)	
Rite	Field	Description	

I	BItS	Field	Description
	7:0	C1_MSB	Bits 15:8 of C1[15:0]
1			

TABLE 43. Compensation Filter C2 LSBs (0x24h)

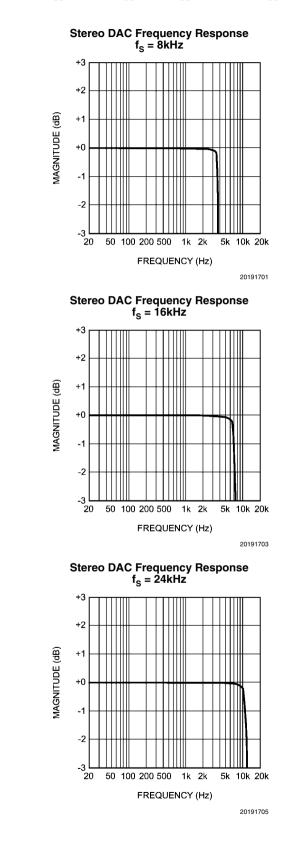
Bits	Field	Description
7:0	C2_LSB	Bits 7:0 of C2[15:0]

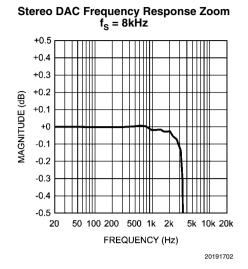
TABLE 44. Compensation Filter C2 MSBs (0x25h)

Bits	Field	Description
7:0	C2_MSB	Bits 15:8 of C2[15:0]

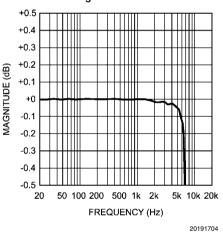
13.0 Typical Performance Characteristics

(For all performance curves AV_{DD} refers to the voltage applied to the A_V_{DD} and LS_V_{DD} pins. DV_{DD} refers to the voltage applied to the D_V_{DD} and PLL_V_{DD} pins; $AV_{DD} = 3.3V$ and $DV_{DD} = 3.3V$ unless otherwise specified.

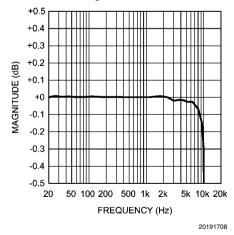




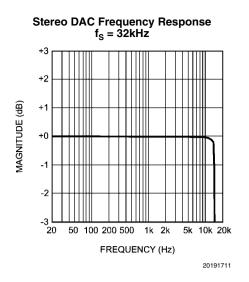
Stereo DAC Frequency Response Zoom f_S = 16kHz



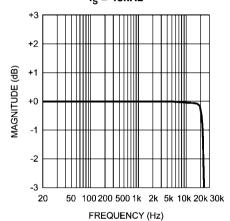
Stereo DAC Frequency Response Zoom $f_S = 24kHz$



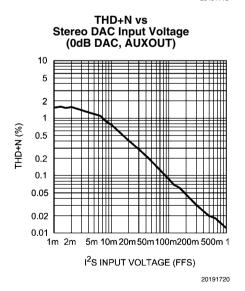
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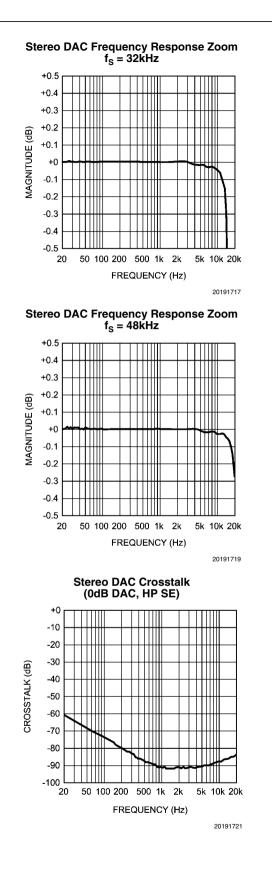


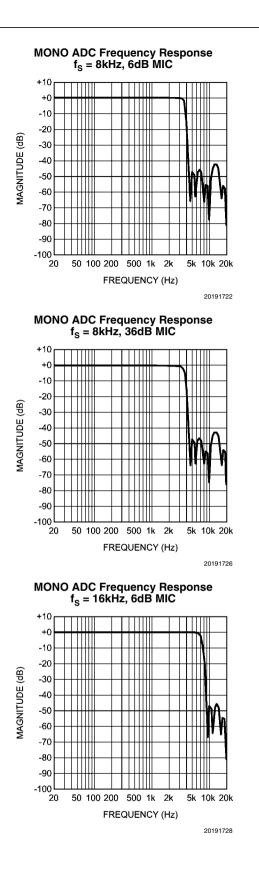


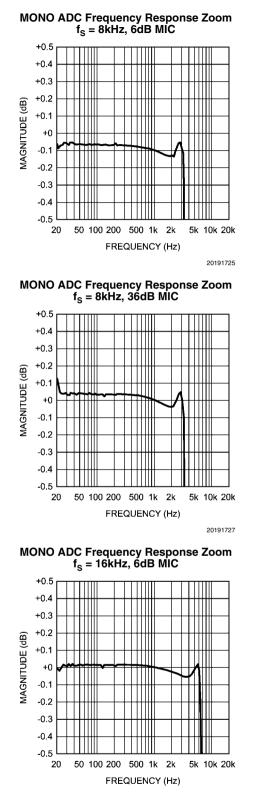


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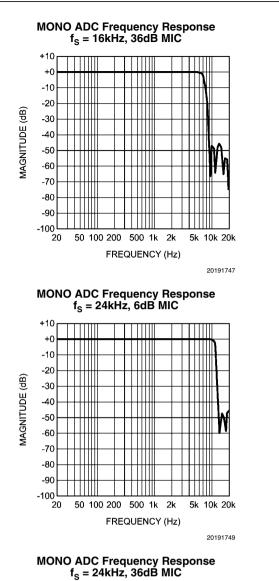


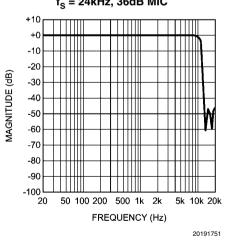


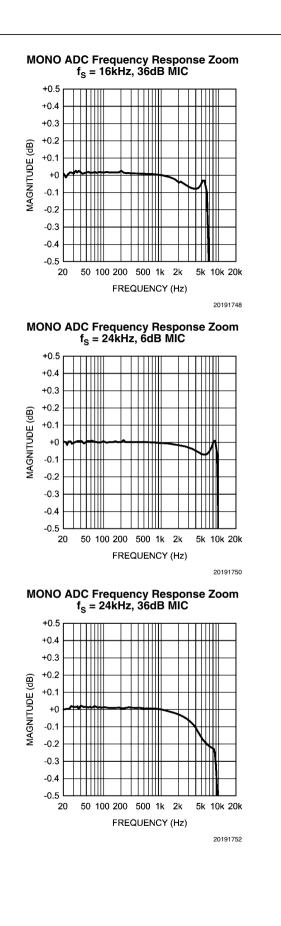


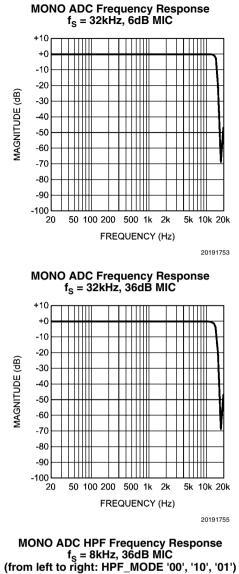
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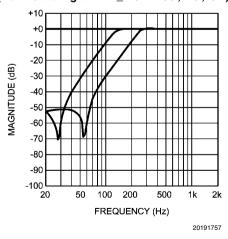
LM49370

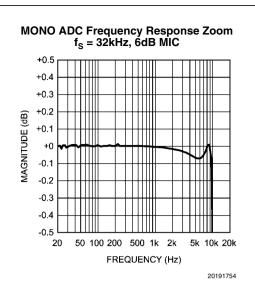




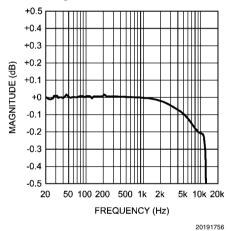




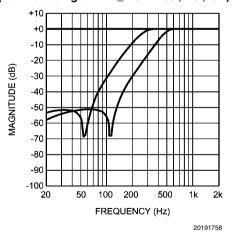




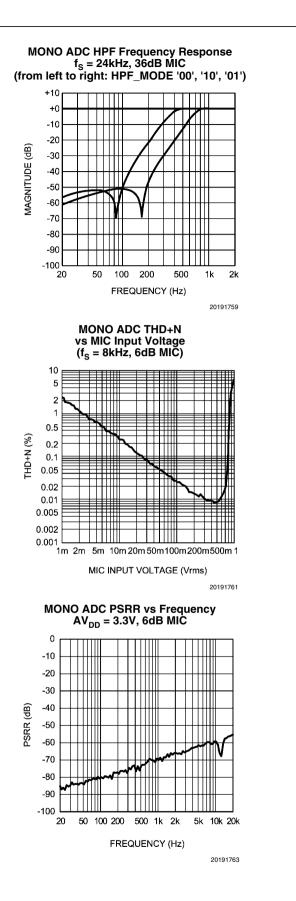
MONO ADC Frequency Response Zoom $\rm f_S$ = 32kHz, 36dB MIC

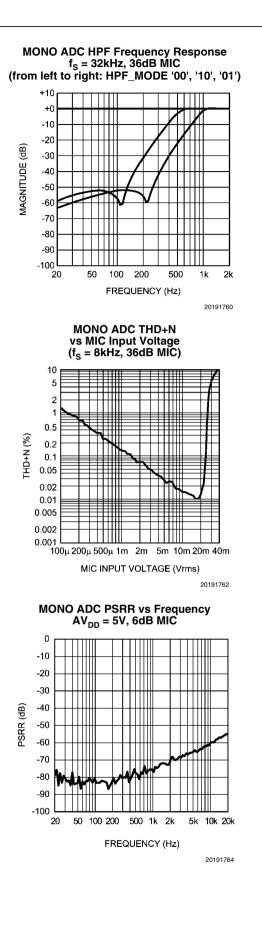


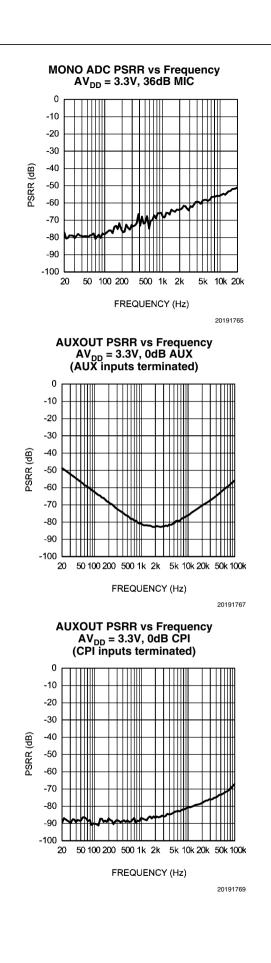
MONO ADC HPF Frequency Response $f_s = 16kHz$, 36dB MIC (from left to right: HPF_MODE '00', '10', '01')

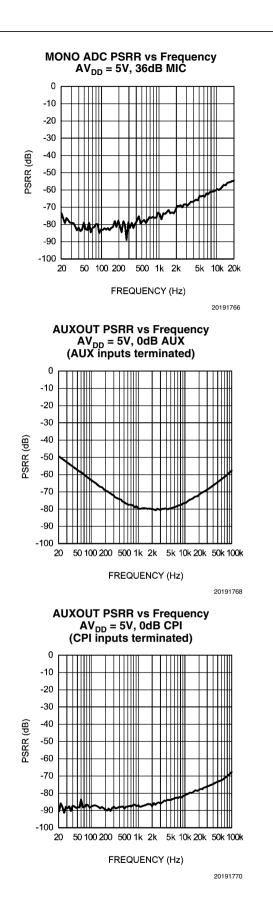


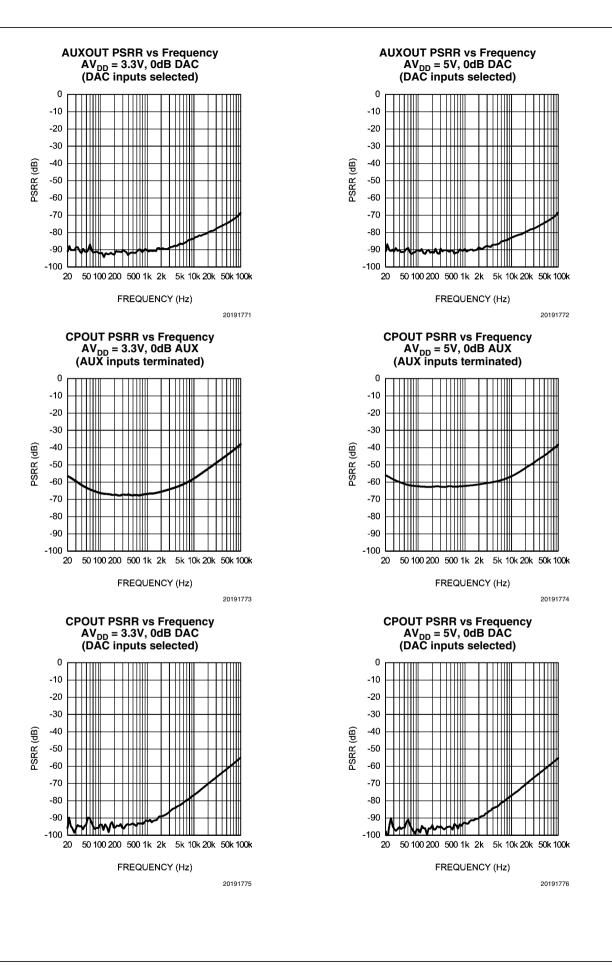


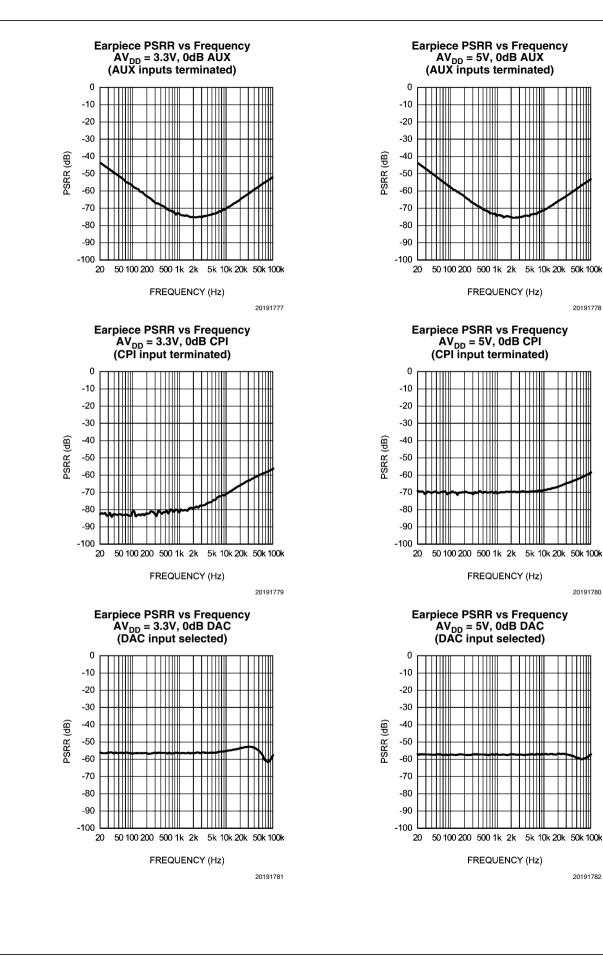


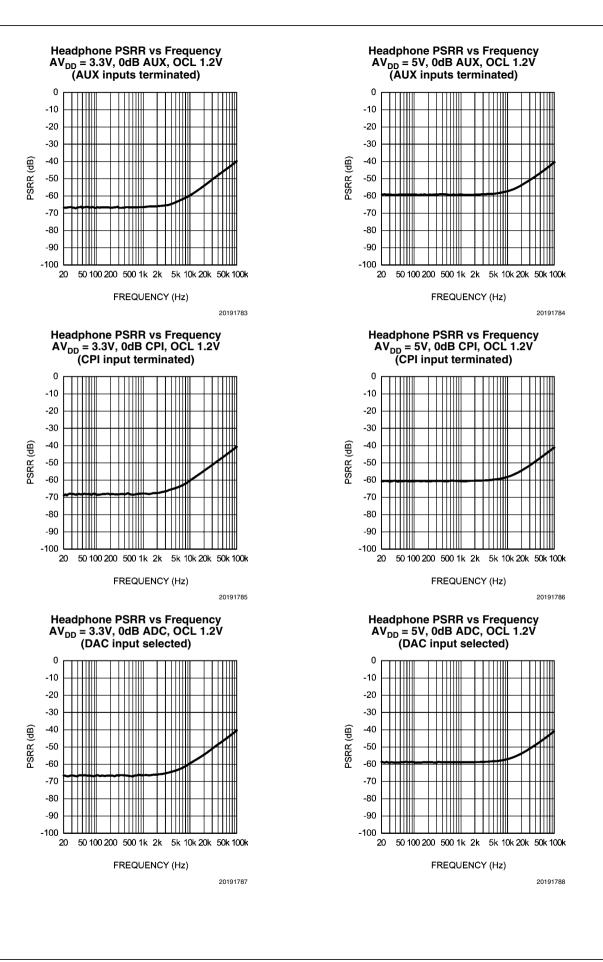


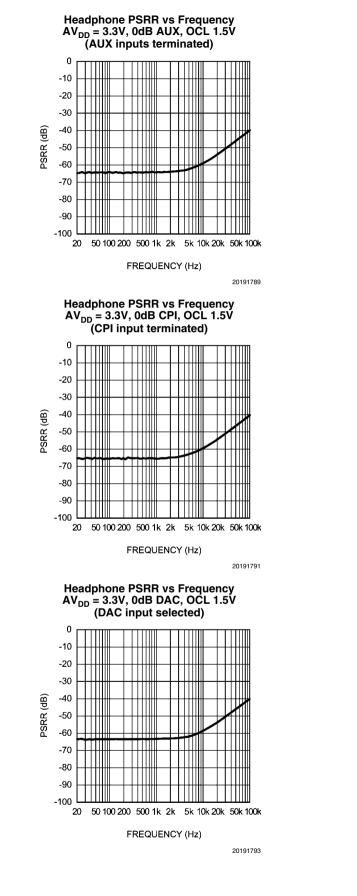


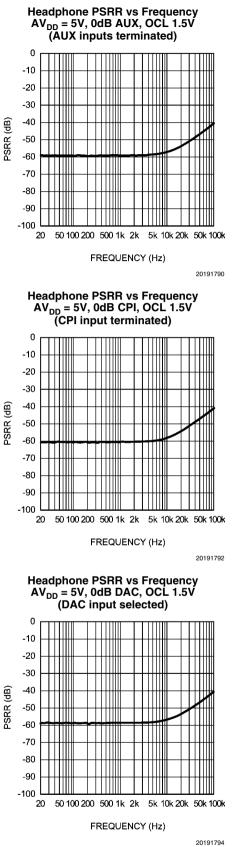


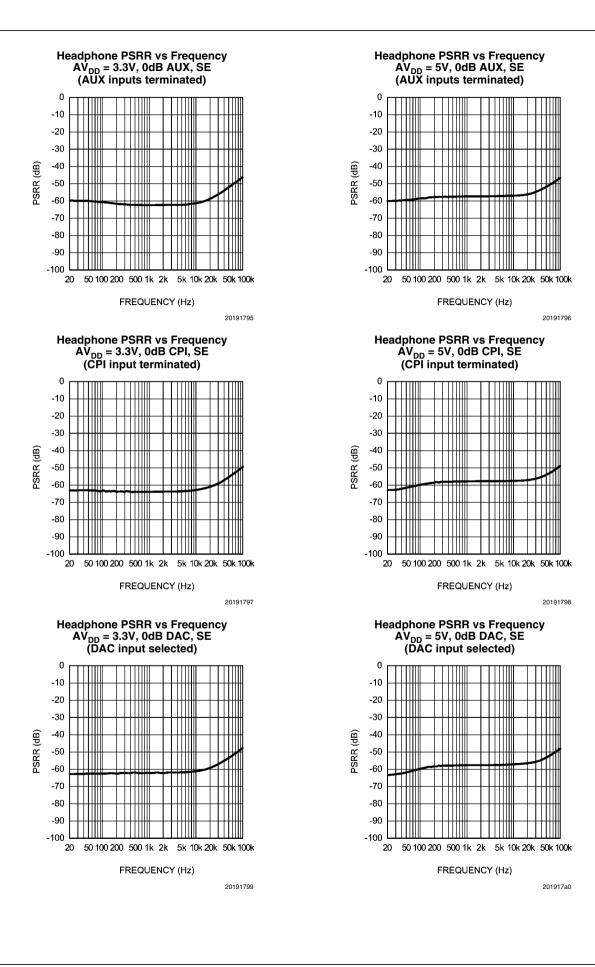




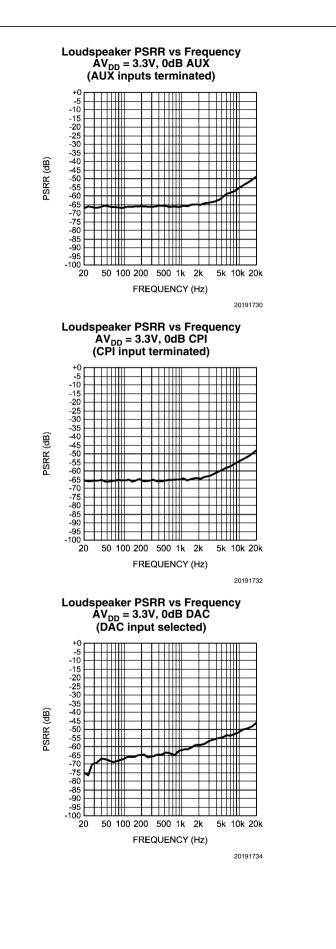


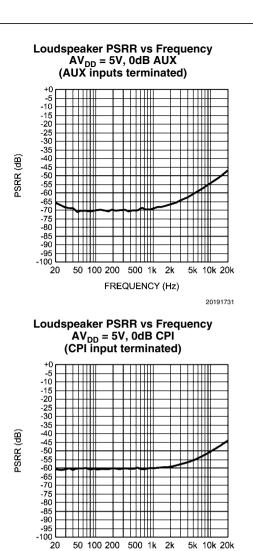






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20191733

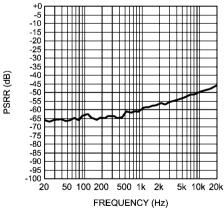
5k 10k 20k

2k

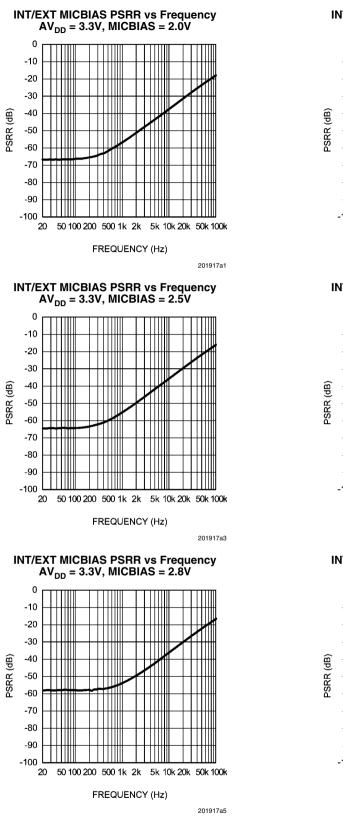
Loudspeaker PSRR vs Frequency AV_{DD} = 5V, 0dB DAC (DAC input selected)

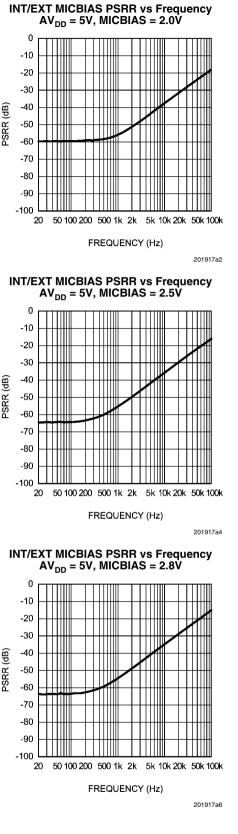
FREQUENCY (Hz)

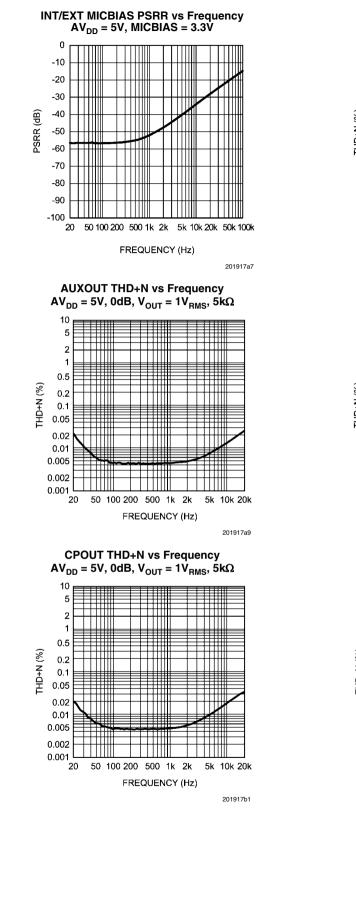
20

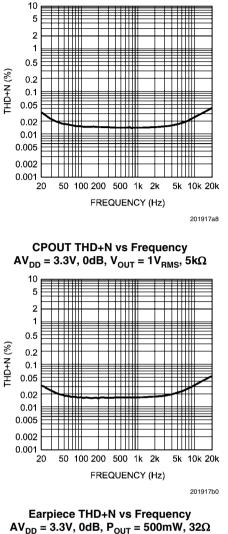


20191735



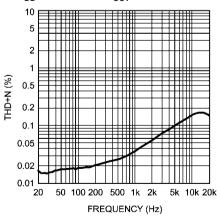




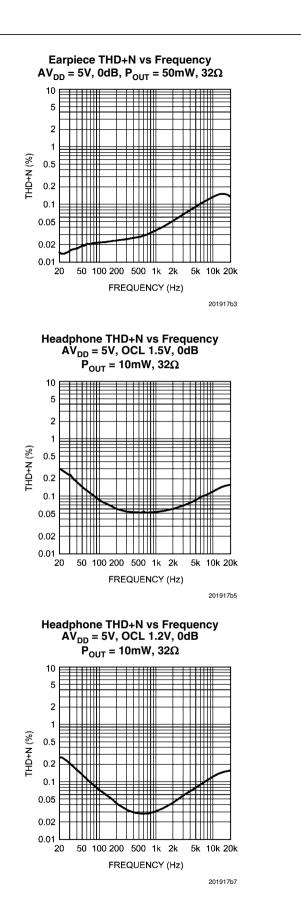


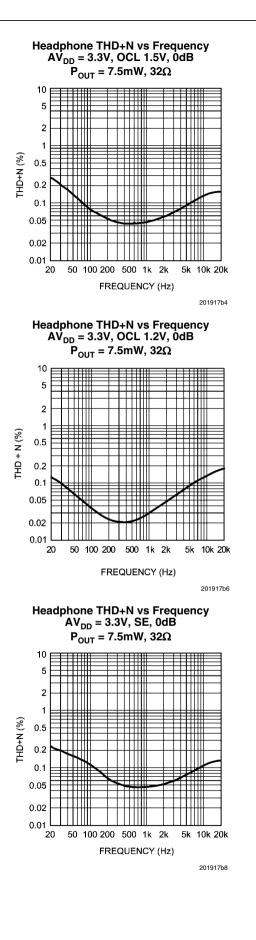
AUXOUT THD+N vs Frequency

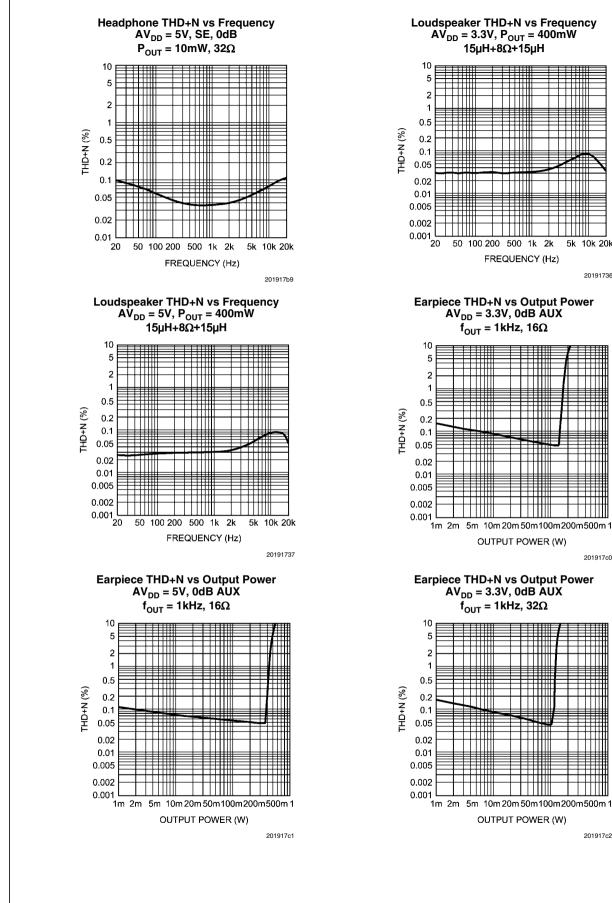
 $AV_{DD} = 3.3V, 0dB, V_{OUT} = 1V_{RMS}, 5k\Omega$



201917b2







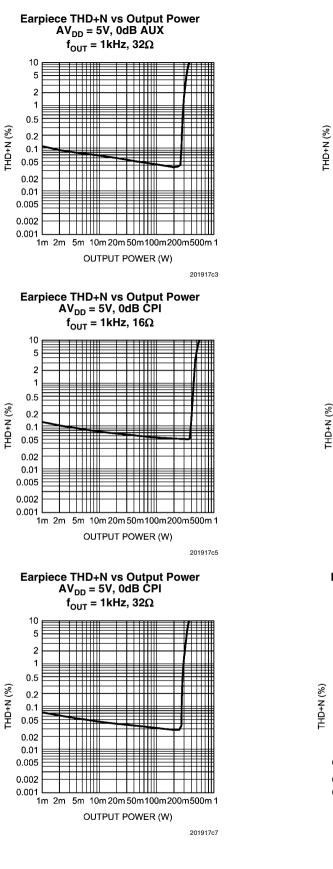
2k

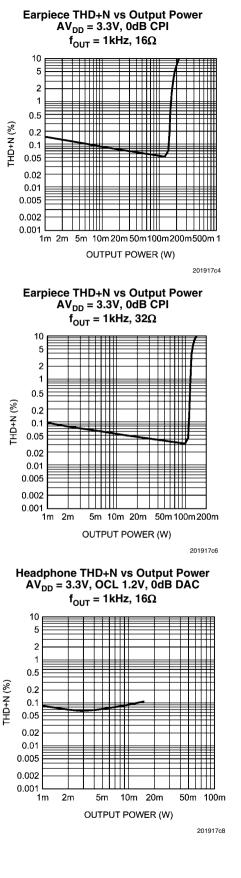
5k 10k 20k

20191736

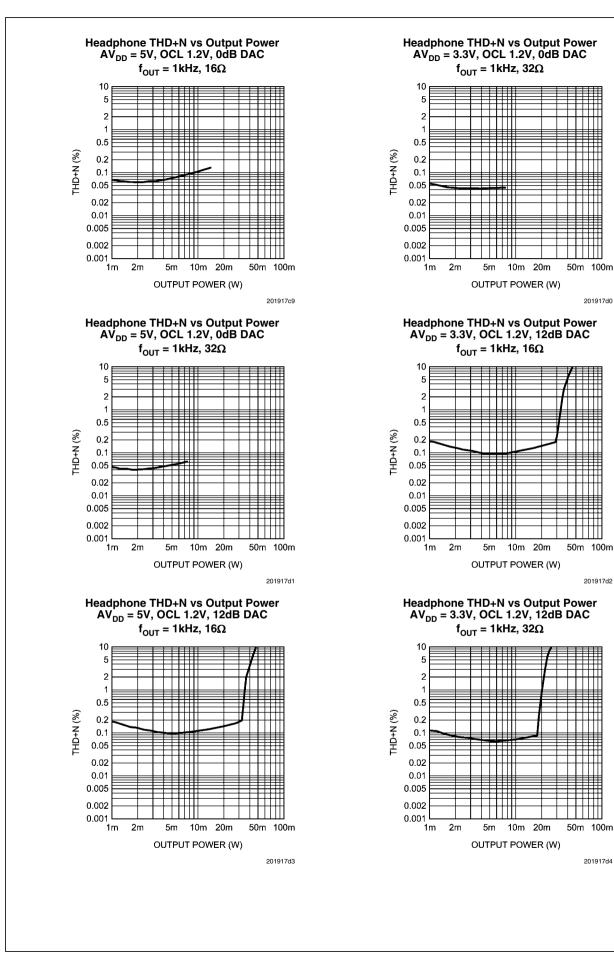
201917c0

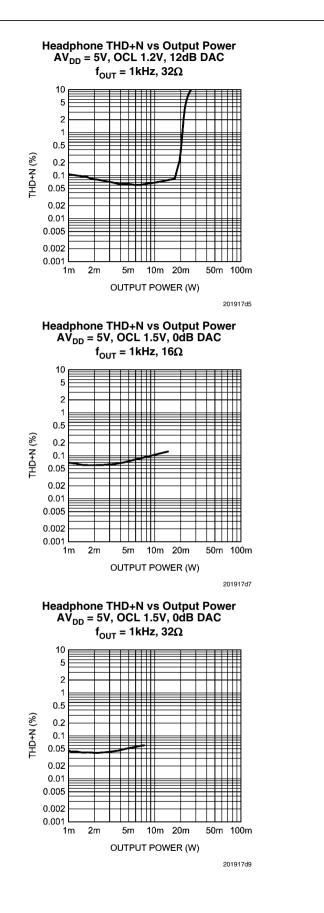
201917c2

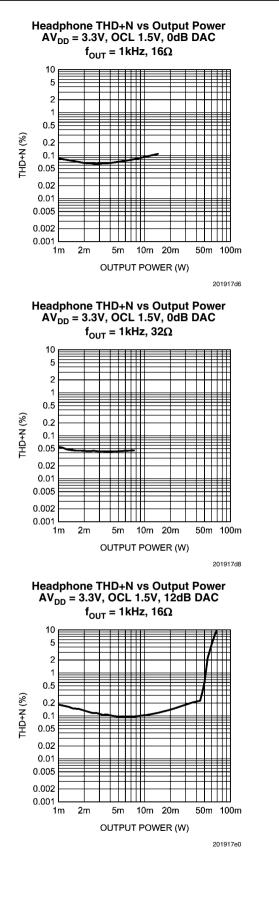




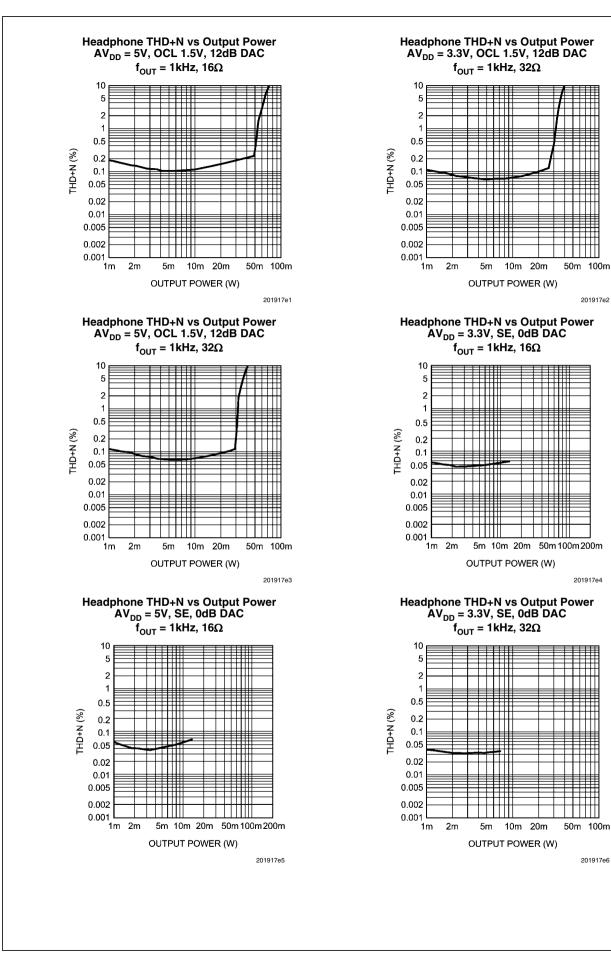












50m 100m 200m

10m 20m

20m

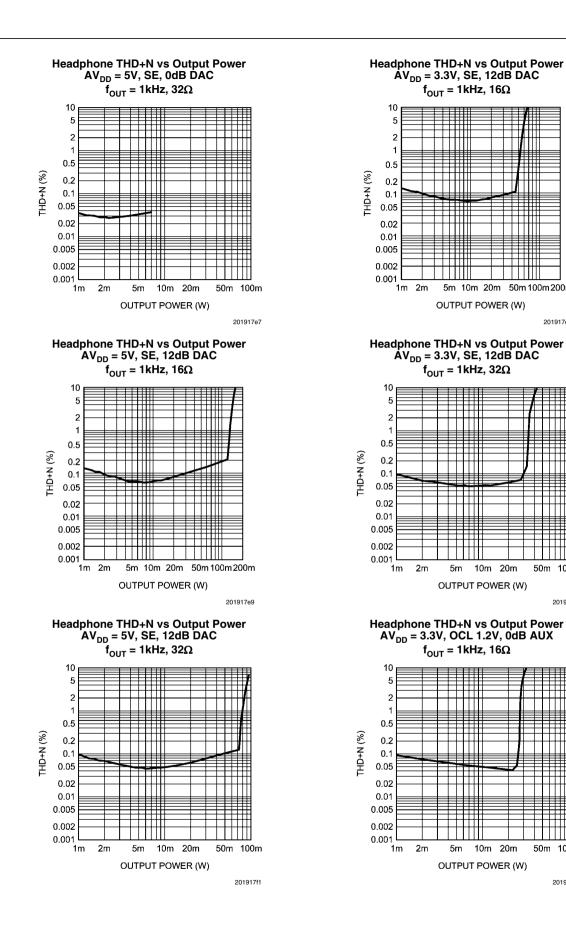
50m 100m

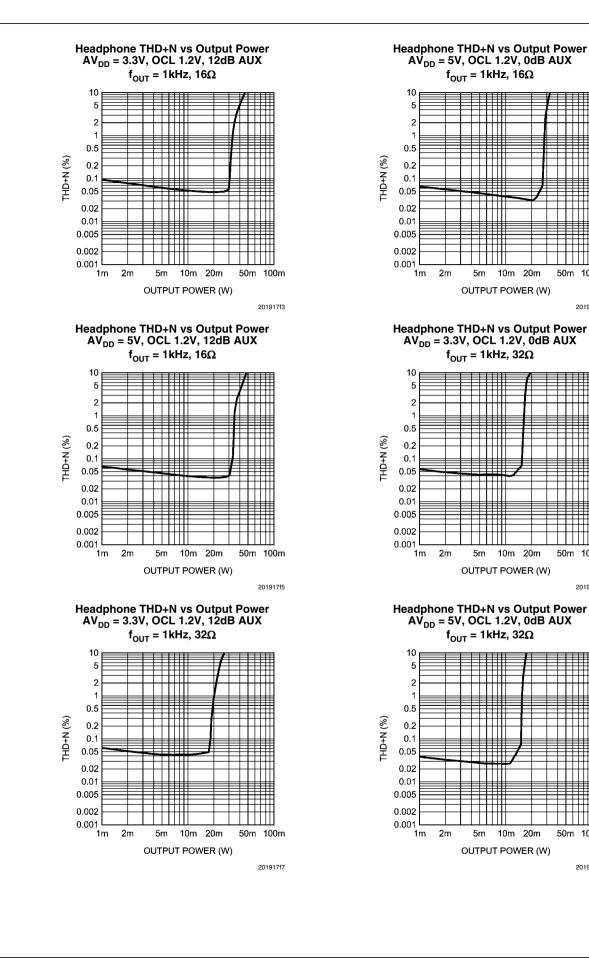
201917f2

201917e8

50m 100m

201917f0





50m 100m

201917f4

20m

20m

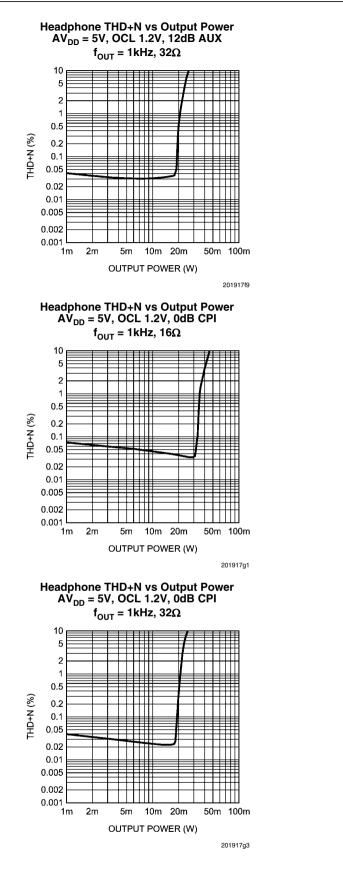
20m

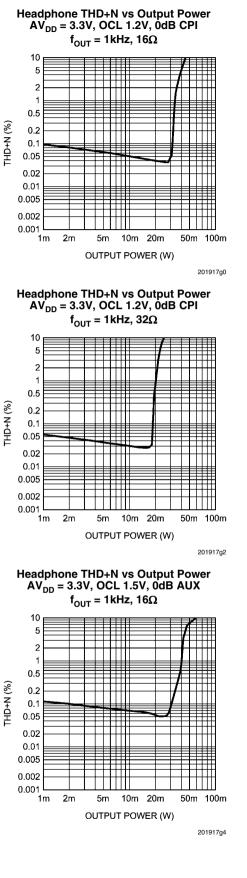
50m 100m

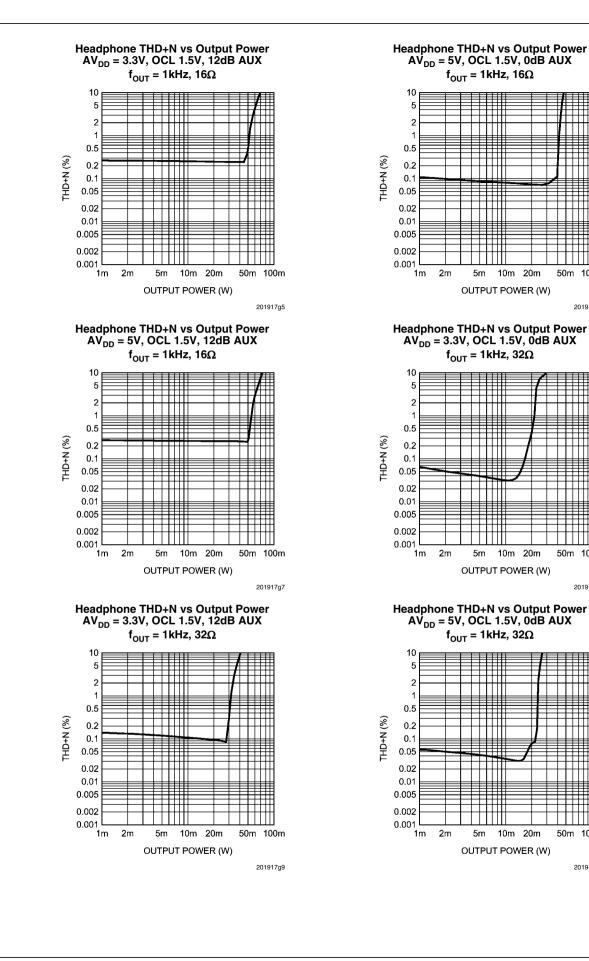
201917f8

50m 100m

201917f6







50m 100m

201917g6

20m

20m

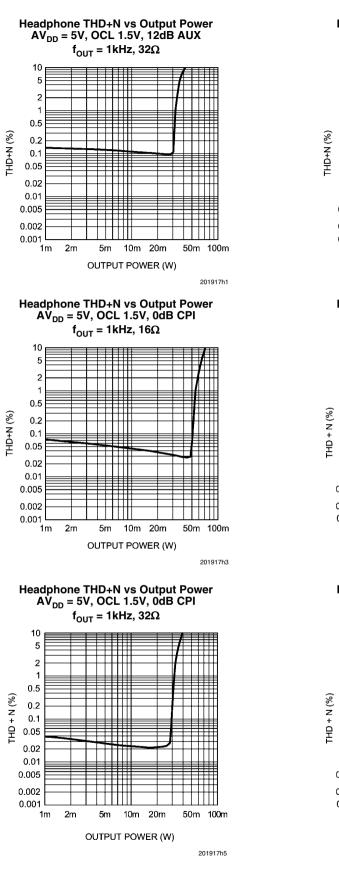
20m

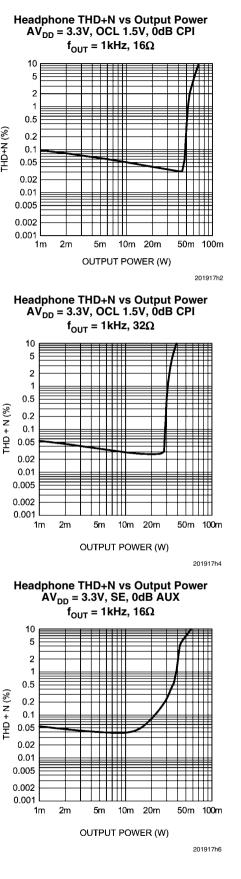
50m 100m

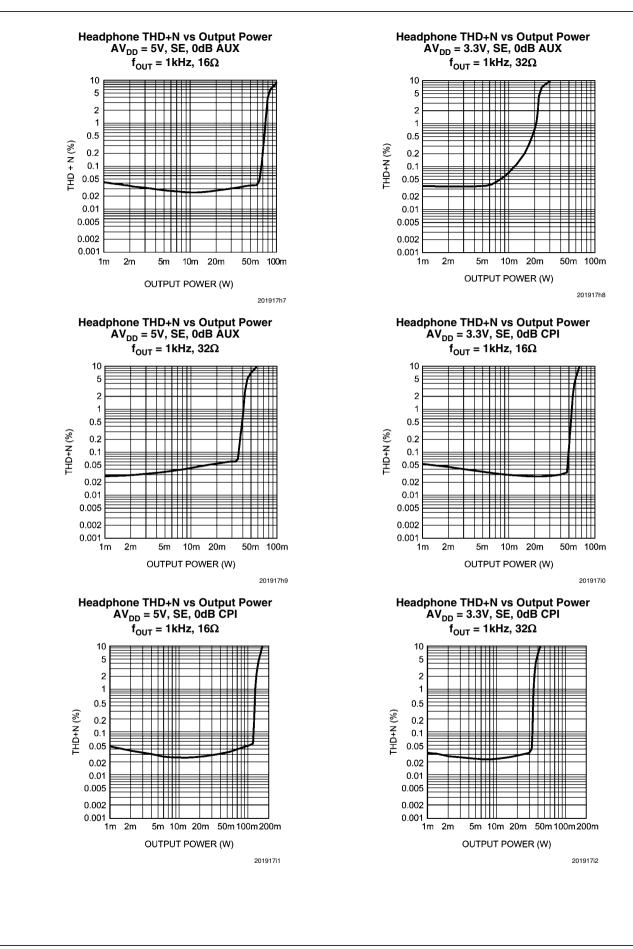
201917h0

50m 100m

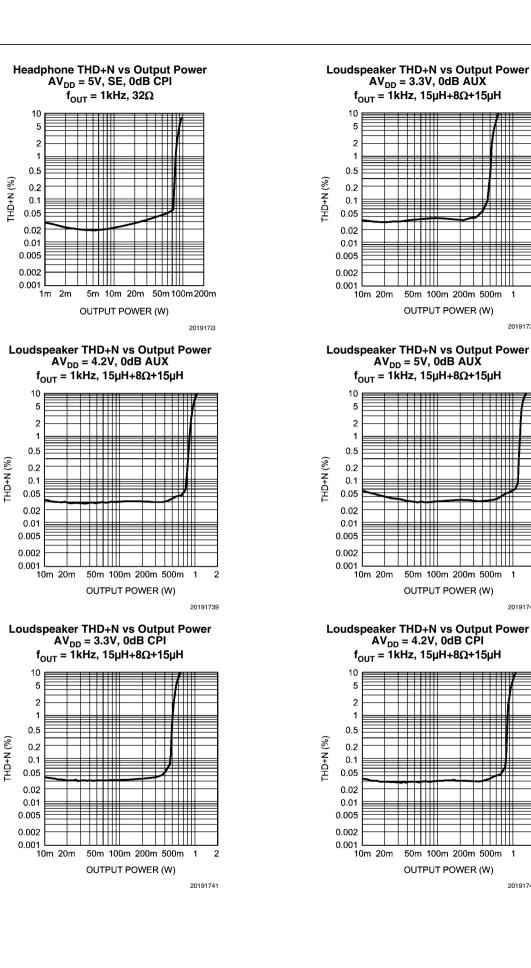
201917q8

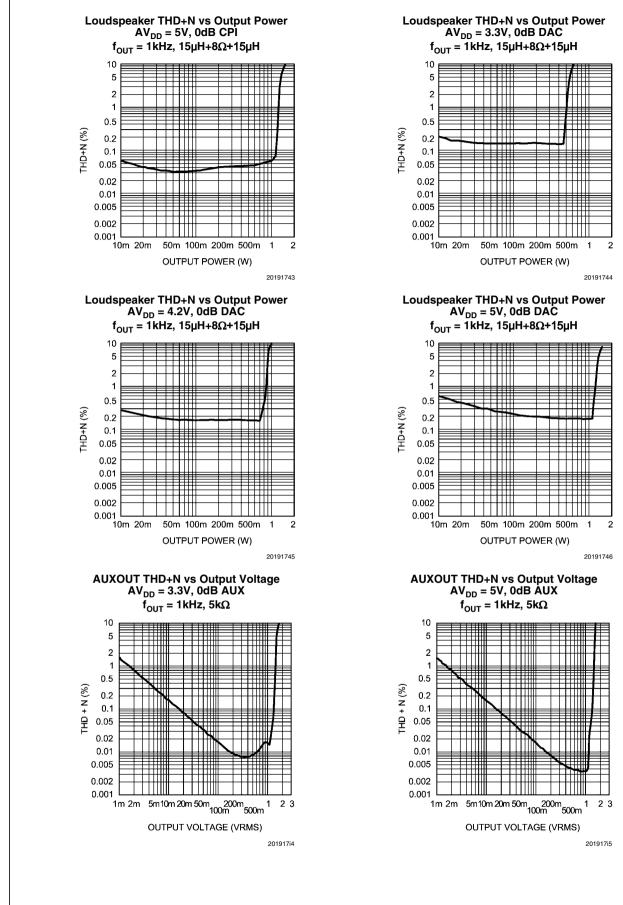


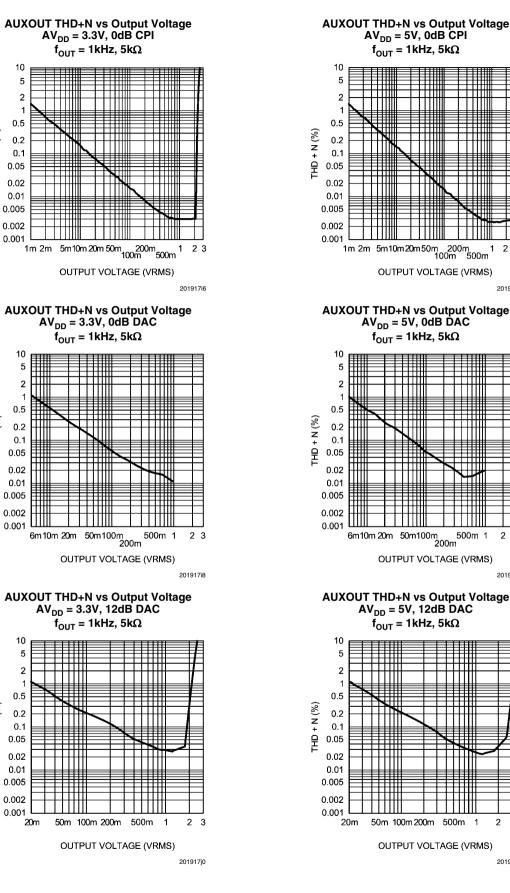




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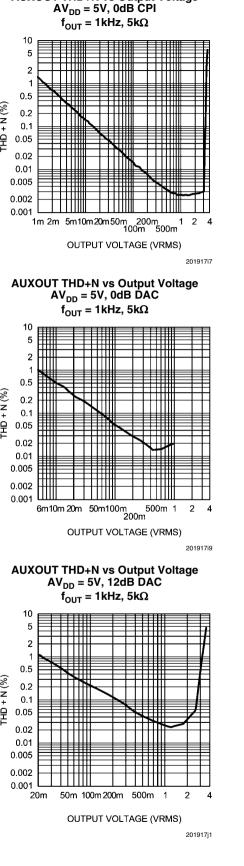


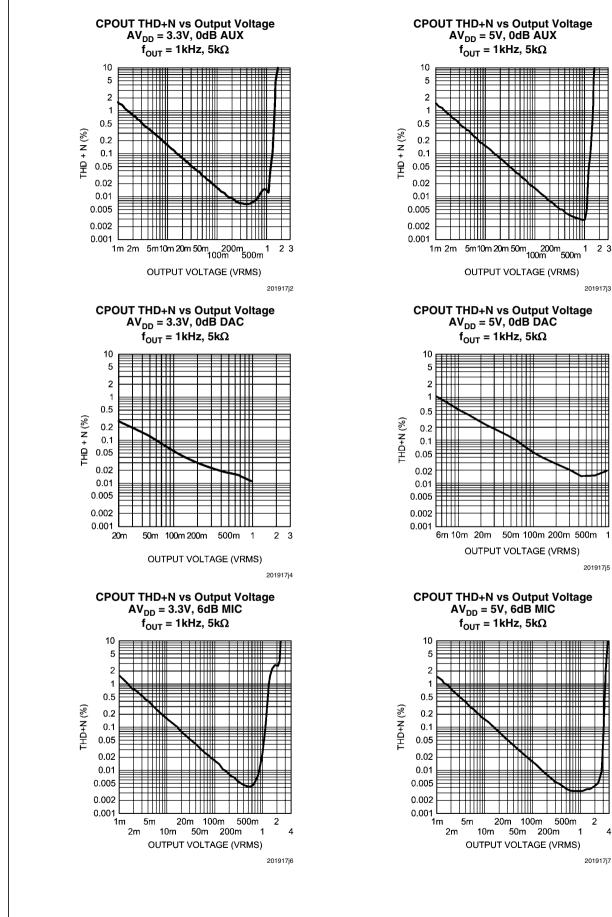


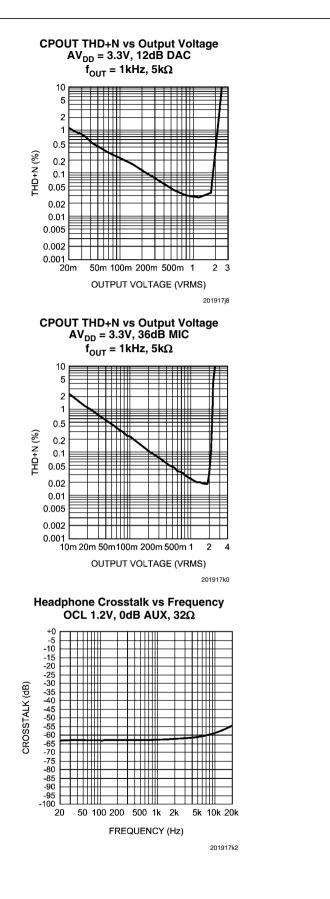
THD + N (%)

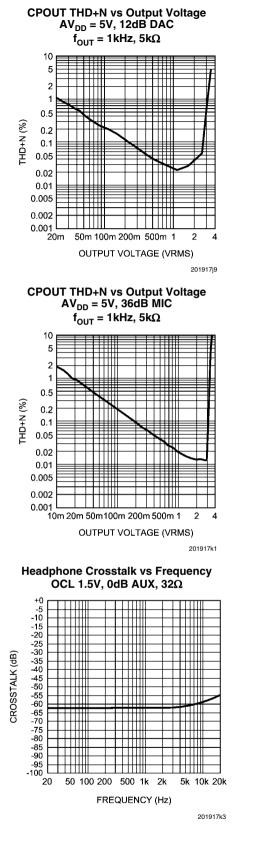
(%) N + OHJ

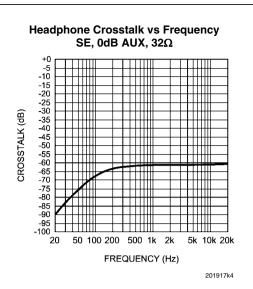
THD + N (%)

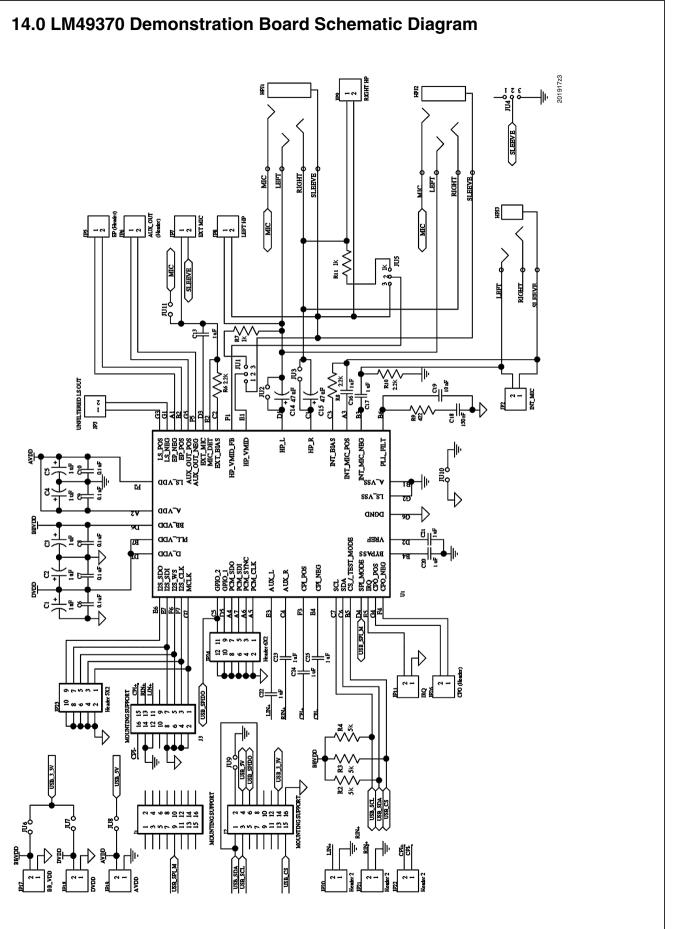




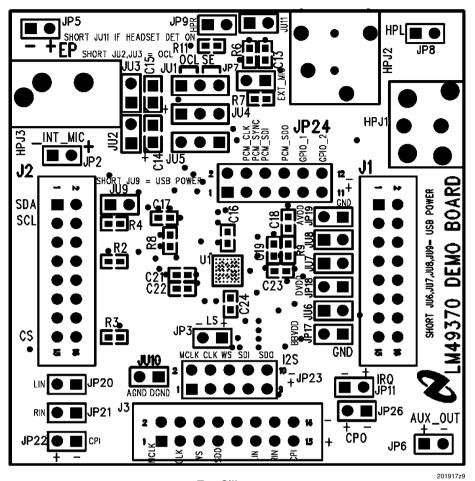




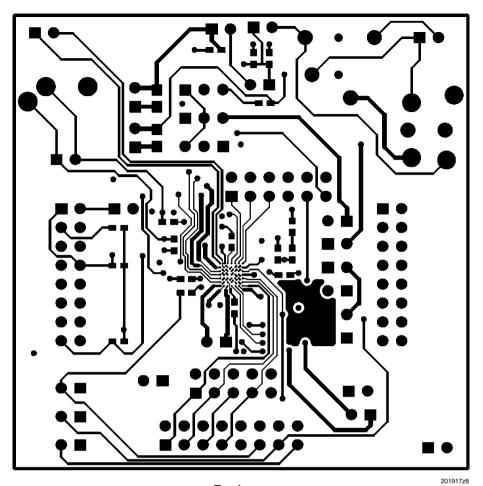




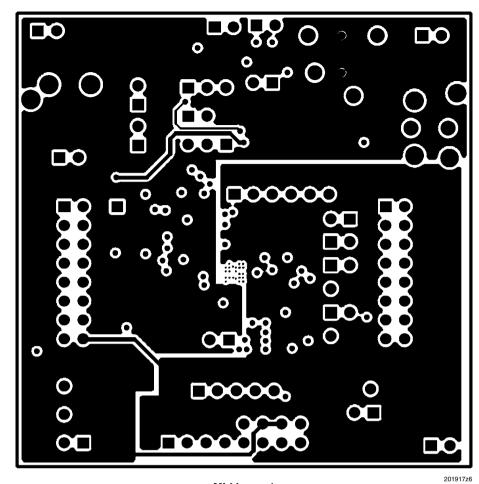
15.0 Demoboard PCB Layout



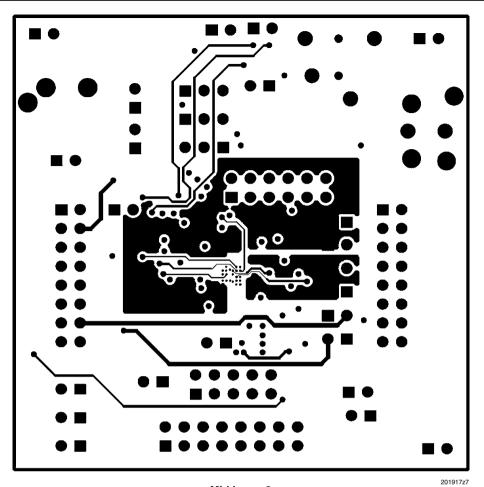
Top Silkscreen



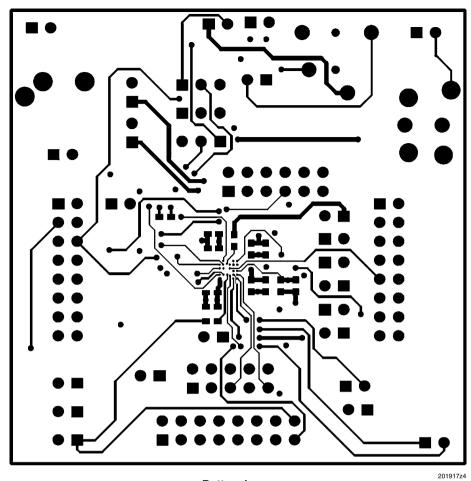
Top Layer



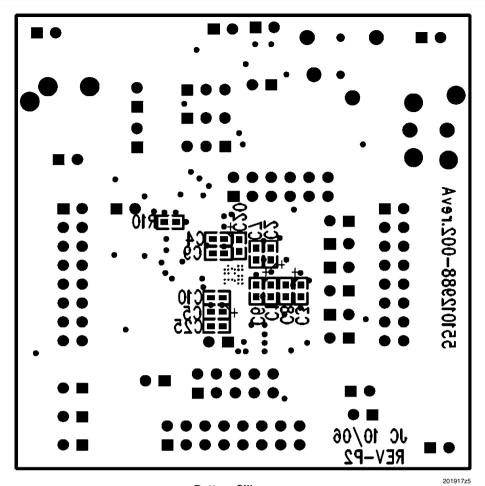
Mid Layer 1



Mid Layer 2



Bottom Layer

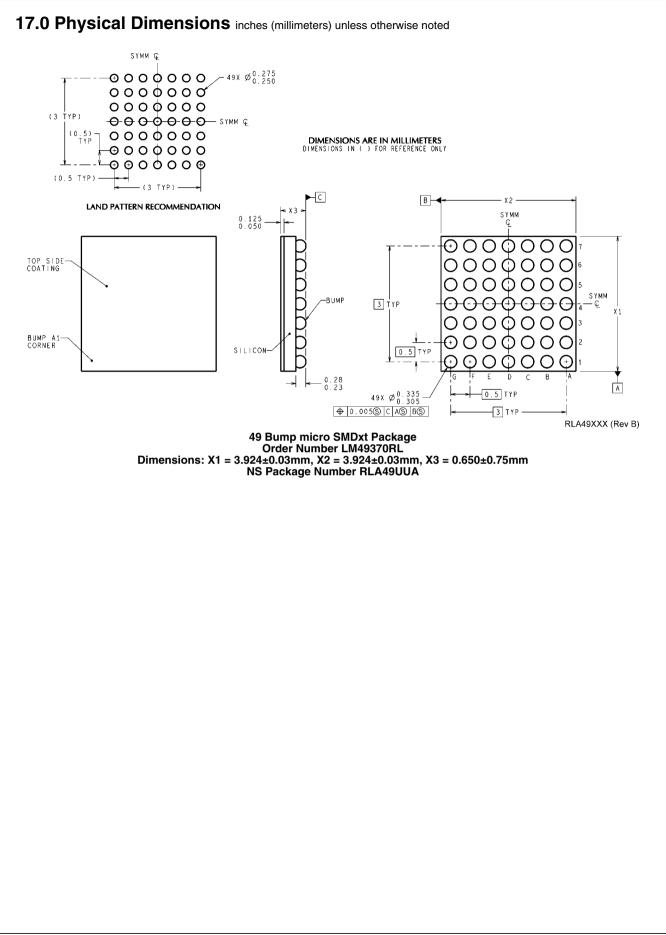


Bottom Silkscreen

16.0 Revision History

Rev	Date	Description
1.0	02/14/07	Initial released.

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Notes

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